**Planck**

**intermediate results**

**XLVI. Reduction of large-scale systematic effects in HFI polarization maps and estimation of the reionization optical depth**


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**ABSTRACT**

This paper describes the identification, modelling, and removal of previously unexplained systematic effects in the polarization data of the Planck High Frequency Instrument (HFI) on large angular scales, including new mapmaking and calibration procedures, new and more complete end-to-end simulations, and a set of robust internal consistency checks on the resulting maps. These maps, at 100, 143, 217, and 353 GHz, are early versions of those that will be released in final form later in 2016. The improvements allow us to determine the cosmic reionization optical depth \( \tau \) using, for the first time, the low-multipole EE data from HFI, reducing significantly the central value and uncertainty, and hence the upper limit. Two different likelihood procedures are used to constrain \( \tau \) from two estimators of the CMB E- and B-mode angular power spectra at 100 and 143 GHz, after debiasing the spectra from a small remaining systematic contamination. These all give fully consistent results. A further consistency test is performed using cross-correlations derived from the Low Frequency Instrument maps of the Planck 2015 data release and the new HFI data. For this purpose, end-to-end analyses of systematic effects from the two instruments are used to demonstrate the near independence of their dominant systematic error residuals. The tightest result comes from the HFI-based \( \tau \) posterior distribution using the maximum likelihood power spectrum estimator from EE data only, giving a value 0.055 ± 0.009. In a companion paper these results are discussed in the context of the best-fit Planck ΛCDM cosmological model and recent models of reionization.

**Key words.** cosmology: observations – dark ages, reionization, first stars – cosmic background radiation – space vehicles: instruments – instrumentation: detectors

1. Introduction

The E-mode polarization signal of the cosmic microwave background (CMB) at multipoles less than 15 is sensitive to the value of the Thomson scattering optical depth \( \tau \). In polarization at large angular scales, the extra signal generated by reionization dominates over the signal from recombination. Cosmic microwave background polarization measurements thus provide an important constraint on models of early galaxy evolution and star formation, providing the integrated optical depth of the entire history of reionization, which is complementary information to the lower limit on the redshift of full reionization provided by Lyman-\( \alpha \) absorption in the spectra of high redshift objects (see Dijkstra 2014; Mashian et al. 2016; Robertson et al. 2015; Bouwens et al. 2015; Zitrin et al. 2015, for recent results and reviews). The reionization parameter \( \tau \) is difficult to constrain with CMB temperature measurements alone as the TT power spectrum depends on the combination \( A_s e^{-2\tau} \), and \( \tau \) is degenerate with \( A_s \), the amplitude of the initial cosmological scalar perturbations.

The B-mode polarization signal at low multipoles is created by the scattering of primordial tensor anisotropies in the CMB by...
reionized matter. This signal scales roughly as $\tau^2$. The value of $\tau$ is thus also important for experiments constraining the tensor-to-scalar ratio, $r$, using the reionization peak of the $B$ modes.

Owing to the large angular scale of the signals, $\tau$ has been measured only in full-sky measurements made from space. Hinshaw et al. (2013) report $\tau = 0.089 \pm 0.014$ from the WMAP9 analysis. Planck Collaboration XI (2016) used Planck\(^1\) polarized 353-GHz data to clean the WMAP Ka, $Q$, and $V$ maps of polarized dust emission, and WMAP $K$-band as a template to remove polarized synchrotron emission, lowering $\tau$ from WMAP data alone by about $1\sigma$ to $\tau = 0.075 \pm 0.013$. Planck Collaboration XIII (2016) used 70-GHz polarization data at low multipoles, which were assumed to be nearly noise-limited (see Sect. 4 below for new estimates of systematic effects) and were cleaned using 353 GHz and 30 GHz to remove dust and synchrotron emission. This low-multipole likelihood alone gave $\tau = 0.067 \pm 0.023$. In combination with the Planck high-multipole $TT$ likelihood, it gave $\tau = 0.078 \pm 0.019$. The combination Planck$TT+ten$sing gave a comparable value of $\tau = 0.070 \pm 0.024$.

The HFI 100 and 143-GHz low-multipole polarization data combined with 353-GHz to remove the Galactic dust foreground could provide tighter constraints on $\tau$, reducing uncertainties by nearly a factor of about two with respect to the results quoted above; however, systematic errors remaining in the HFI polarized data at large angular scales in the 2015 Planck release led the Planck collaboration to delay their use. Since the time when the data for the 2015 release were frozen, we have made substantial improvements in the characterization and removal of HFI systematic errors, which we describe in this paper. The maps, simulations, and sometimes computer codes used here are referred to as “pre-2016”, and are nearly identical to those in the 2016 data release to come. We note that the HFI submillimetre channels at 545 and 857 GHz are not polarization sensitive and their improvement is not discussed in this paper.

The paper is structured in the following way. Section 2 analyses systematic errors affecting the HFI time-ordered information processing, describes tests of these errors, and describes new versions of polarized mapmaking and calibration. Section 3 discusses global tests of HFI polarization at the power spectrum level. Section 4 discusses quality tests of Low Frequency Instrument (LFI) polarization data. Section 5 describes component separation and cross-spectra and their suitability for the measurement of $\tau$. Section 6 describes the likelihood analysis of the $\tau$ parameter. Finally Sect. 7 discusses the implications of our new $\tau$ value.

These data described here are also used in an accompanying paper (Planck Collaboration Int. XLVII 2016) to constrain different models for the reionization history of the Universe.

2. Improvements of HFI mapmaking and calibration for low multipoles

2.1. Overview

Analysis of HFI polarization systematic effects is complex and technical in nature. This paper, together with

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1 Planck (http://www.esa.int/Planck) is a project of the European Space Agency (ESA), with instruments provided by two scientific consortia funded by ESA member states and led by Principal Investigators from France and Italy, telescope reflectors provided through a collaboration between ESA and a scientific consortium led and funded by Denmark, and additional contributions from NASA (USA).

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Planck Collaboration VII (2016), completes the characterization of the HFI time-ordered information (TOI) products, extending analysis of the polarization power spectra to the lowest multipoles.

The HFI TOI used in this paper are described in the 2015 data release (Planck Collaboration VII 2016), and a calibrated version is publicly available in the Planck Legacy Archive\(^2\). The spacecraft pointing solution (Planck Collaboration I 2016) and all instrumental parameters, including the focal plane geometry, cross-polar leakage parameters, and polarization angle parameters, are identical to those used in the 2015 release.

HFI systematic errors have been discussed extensively in earlier papers (Planck Collaboration X 2014; Planck Collaboration VII 2016) and were shown to be under control on small angular scales. Large angular scales, however, were still affected by not-fully-understood systematic effects.

The reduction of systematic errors in HFI polarization measurements at large angular scales reported in this paper is the result of applying a new mapmaking code, Srollo. Srollo is a polarized destriping algorithm, similar to the 2015 HFI mapmaking pipeline (Planck Collaboration VIII 2016), but it solves simultaneously for absolute calibration, leakage of temperature into polarization, and various other sources of systematic error. Systematic residuals are removed via template fitting, using HEALPix-binned rings (HPR) to compress the time-ordered information. Each HPR consists of data from a given stable pointing period (ring) binned into HEALPix pixels (Górski et al. 2005). A version of this code with minor additions will be used for the final Planck data release in 2016. In its present form, Srollo reduces the systematic errors in the HFI $EE$ polarization spectra at multipoles $\ell \geq 2$ to levels close to the nominal instrumental noise. This allows a measurement of the reionization optical depth $\tau$ from the HFI alone, which was not possible at the time of the 2015 Planck data release.

The rest of this section discusses each of the specific improvements. Section 2.2 introduces the end-to-end simulations used in this paper. Section 2.3 analyses the detector system noise, which sets a fundamental limit to the measurement of the polarization spectra and to $\tau$ with HFI data. (Appendix A summarizes a number of effects removed in the TOI processing that make a negligible contribution to the systematic error budget of polarization measurements at large angular scales.) Section 2.4 describes removal of the zodiacal light, and far side lobes. Section 2.5 characterizes the systematic errors induced by non-linearities in the analogue-to-digital converters (ADCs) used in the bolometer readout electronics. These non-linearities, if uncorrected, would be the dominant source of systematic errors in polarization at large angular scales. Section 2.6 discusses all other systematic errors not corrected after the TOI processing, and mitigated by Srollo.

2.2. End-to-end simulations

End-to-end (E2E) HFI simulations, introduced for the first time in 2015 (Planck Collaboration XI 2016), include an accurate representation of the response of the instrument to sky signals, as well as known instrumental systematic errors at the TOI or ring level, all of which are propagated through the entire analysis pipeline to determine their effect on the final maps. The version used in this paper runs the pre-2016 Srollo1 mapping code, described in detail in Sect. B.3. Simulations built with this pre-2016 pipeline are referred to as HFI focal plane simulations

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2 http://archives.esac.esa.int/pla
Detector noise is determined through a multi-step process, starting with first-order correction of the TOI for ADC non-linearity, demodulation, deglitching, 4-K line removal, and time-response deconvolution. The sky signal is then estimated (using the redundancy of multiple scans of the same sky during each stable pointing period) and removed, leaving the noise, which can then be characterized (see Planck Collaboration VII 2016, for details).

Within a frequency band, the noise power spectrum of each bolometer has a similar shape below 5 Hz. Figure 1 shows the mean noise spectrum for each of the polarization-sensitive HFI channels, normalized to unity at 0.25 Hz (we are interested here in the shapes of the noise spectra, not their absolute amplitude).

Detector noise can be divided into three components (see Fig. 2), with spectra varying approximately as $f^0$ (i.e., white), $f^{-2}$, and $f^{-1}$. The $f^0$ and $f^{-1}$ components are uncorrelated between detectors; however, the $f^{-2}$ component is correlated between detectors. This component dominates below $10^{-2}$ Hz, and thus below the spin frequency. Noise levels at frequencies around 0.002 Hz (much below the spin frequency) changed during the mission, reflecting variations of the Galactic cosmic ray flux with solar modulation and their effect on the temperature of the bolometer plate. These effects are corrected using a template built from the signal of the dark bolometers smoothed on minute timescales (Planck Collaboration VI 2014). The $f^{-2}$ component is different for spider-web bolometers (SWBs, red curves) and polarization-sensitive bolometers (PSBs, blue curves). Common glitches seen in the two silicon wafers of a PSB produce correlated noise with a knee frequency of about 0.1 Hz (Planck Collaboration X 2014). Above 0.2 Hz, the correlated noise is at a level of 1% of the total detector noise; at twice the spin frequency (multipole $\ell = 2$ in the maps), it contributes only 10% of the total noise.

After removal of the correlated part, an uncorrelated $f^{-1}$ component remains (green curve in Fig. 2) that has $f_{\text{knee}} \approx 0.2$ Hz for all HFI detectors (see, e.g., Fig. 13 of Planck Collaboration X 2014). Above this frequency the noise is predominantly white, with amplitude in good agreement with ground-based measurements. The 10-M$\Omega$ resistor and the capacitor in the focal plane, read out through the same electronics as the bolometers, show only 1/f noise below 3 mHz, showing that this additional 1/f component is not generated in the readout. The 1/f component of the noise is discussed in Sect. A.1, and is well approximated by a Gaussian statistical distribution, as seen in Fig. 3. The low level ($<10^{-3}$) non-Gaussian wings which are cut by the 3.3$\sigma$ clipping of the deglitching algorithm, are not seen on 100-ring averages, which suggest that they are caused by rare events.

1/f noise around 0.06 Hz is largely uncorrelated, and is constant during the mission within uncertainties. This confirms that undetected glitches do not contribute significantly, apart from a small contribution near the spin frequency. No intrinsic 1/f noise was detected in individual bolometer ground tests, but a 1/f component was seen in HFI focal plane unit ground calibration measurements below 0.1 Hz (see, e.g., Fig. 10 of Lamarre et al. 2010), comparable to those seen in flight. Nevertheless a thermal fluctuation residual cannot be excluded.

In summary, the correlated component ($f^{-2}$) between all bolometers is mostly removed by the dark bolometer baseline removal. The weak correlated white noise (1%) between pairs of bolometers within a PSB, caused by undetected glitches, is not removed by this baseline removal procedure. The one-minute smoothing of the dark bolometer timeline used to remove this common thermal mode will leave a small correlated residual in the frequencies just above the spin frequency. Furthermore the ADC non-linearities discussed later will affect differently
each bolometer and introduce some uncorrelated residuals which might account for at least part of this $1/f$ component.

In conclusion, the component of TOI noise that is uncorrelated between detectors (except near the spin frequency) can be modelled with two Gaussian components, white and $1/f$. These are taken from version 8 of the FFP8 noise model Planck Collaboration XII (2016), adjusted to the power spectrum observed in the half-ring null tests. The TOI noise, and its propagation to maps and power spectra, is taken in this paper as the fundamental limitation of HFI, and the maps built with FFP8 noise give the reference for maps and power spectra in simulations.

2.4. Sky components removed in the ring making

2.4.1. Removal of zodiacal dust emission

Thermal emission from interplanetary dust – the zodiacal emission – varies not only with frequency and direction, but also with time as *Planck* moves through the solar system. The size of the effect on temperature is small, as estimated in Planck Collaboration VIII (2016), and it was not removed from the TOI released in 2015. Rather, we reconstruct the emission using the COBE Zodiacal Model (Kelsall et al. 1998) and the zodiacal emissivity parameters found in Planck Collaboration VIII (2016), and subtract it from the TOI of each detector prior to mapmaking.

The zodiacal emission is not expected to be intrinsically polarized; however, HFI measures polarization by differing the signals from quadruplets of PSBs. Since each detector has a slightly different spectral response, any component that has a different spectrum from the blackbody spectrum of the primordial CMB anisotropies, such as zodiacal emission, can introduce leakage of temperature into polarization. By subtracting a model of zodiacal emission from the TOI of each detector, this source of leakage is strongly suppressed.

Differences between $Q$ and $U$ maps made with and without removal of zodiacal emission show the size of the effect. At 100, 143, and 217 GHz, the zodiacal correction is less than about 100 nK$_{CMB}$. At 353 GHz, it is an order of magnitude larger. If our correction was so poor that it left 25% of the emission, temperature leakage would contribute errors of order 25 nK$_{CMB}$ to the polarization maps at 100, 143, and 217 GHz, and perhaps 100 nK$_{CMB}$ at 353 GHz. The effect on $\tau$ is negligible.

**Table 1.** Estimates of the relative impact of the FSLs per bolometer within a frequency band.

<table>
<thead>
<tr>
<th>Frequency [GHz]</th>
<th>Min [%]</th>
<th>Max [%]</th>
<th>Mean [%]</th>
<th>rms [%]</th>
</tr>
</thead>
<tbody>
<tr>
<td>100 . . . . . . .</td>
<td>0.074</td>
<td>0.101</td>
<td>0.086</td>
<td>0.010</td>
</tr>
<tr>
<td>143 . . . . . . .</td>
<td>0.051</td>
<td>0.059</td>
<td>0.054</td>
<td>0.002</td>
</tr>
<tr>
<td>217 . . . . . . .</td>
<td>0.048</td>
<td>0.053</td>
<td>0.051</td>
<td>0.002</td>
</tr>
<tr>
<td>353 . . . . . . .</td>
<td>0.015</td>
<td>0.016</td>
<td>0.016</td>
<td>&lt;0.001</td>
</tr>
</tbody>
</table>

Notes. The table lists the minimum, maximum, average, and rms values between the bolometers of one frequency band. These numbers are computed by convolving the FSLs with the dipole and propagating the resulting signal to the maps and power spectra to include the filtering of the destriper.

2.4.2. Far sidelobes

HFI far sidelobes (FSLs) are discussed in detail in Planck Collaboration VII (2016). They are dominated by radiation from the feedhorns spilling over the edge of the secondary mirror, and by radiation reflected by the secondary mirror spilling over the edge of primary mirror or the main baffle. The effects of diffraction by edges other than the mouths of the feedhorns themselves is important only at 100 GHz, where diffraction can affect very low multipoles (see below). FSL variations inside a frequency band are negligible at HFI frequencies. The *Planck* optical system is modelled using the GRASP software. Higher-order effects with more than one reflection and diffraction by sharp edges can be computed by GRASP, but the complexity and computational time is a strong function of the order number. We have computed the first-order FSLs for each bolometer, and then checked for a few representative bolometers that the addition of the next seven orders gives small corrections to the first-order computations.

Convolution of the sky maps with the FSL model predicts small contributions to the maps. In addition, the contributions from FSLs close to the spin axis are reduced by destriping during the mapmaking process (a contribution of FSLs on the spin-axis is completely removed by the destriper). The Galactic contributions though the FSLs are similar at 100, 143, and 217 GHz since the decrease in the FSL amplitude and the increase in Galactic emission at higher frequencies roughly compensate each other. The solar dipole FSL contributions decrease with frequency, as summarized in Table 1. The FSLs produce a direct dipole calibration shift by increasing the effective beam etendue, though the shift is reduced by the destriping. The dispersion between detectors is caused by the variation in the main spillover (the rays that miss the secondary mirror), which is dominated by the position of the horns in the focal plane: the bolometers further away from the symmetry axis experience a larger spillover. This effect can be used as an additional test of the fidelity of the GRASP calculations used to model the FSLs.

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3 Here we adopt the convention of following the light from the detectors outwards, as used in the simulations.

The impact of FSLs on the HFI maps depends on the scanning strategy, and so must be corrected in either the TOI processing or in building the HPRs. A FSL model has been computed from the first-order GRASP calculations. Higher-order effects are absorbed, together with other residuals, into the empirical complex transfer functions discussed in Sect. 2.6.2. The parameters of the transfer functions are then determined from the data.

Angular power spectra\(^5\) from HFI pre-2016 E2E simulations of the FSLs are displayed in Fig. 4. At all HFI frequencies, the FSL effects are smaller than the fiducial \(F-EE\) power spectrum by two orders of magnitude, where we define \(F-xx\) (\(F-TT, F-EE, F-BB\)) to be the base ACDM power spectra from best-fit Planck 2015 cosmological parameters (Planck Collaboration XIII 2016) \(\tau = 0.066\) and upper limit \(r = 0.11\).

The FSL signals are removed using GRASP first-order predictions, leaving residuals due to higher orders and uncertainties. These residuals are smaller than the effect displayed in Fig. 4.

Table 1 provides estimates of the effects of FSLs on the relative inter-calibration with respect to the average of all detectors within the same frequency band. As discussed in Sect. 2.4.2, the effect of the FSLs depends on the scanning strategy, and must be removed at the HPR level. The effect on the dipole requires propagation of the FSLs through the HFI pre-2016 E2E simulations to take into account the filtering by the destripper. These numbers can be compared directly with the main beam dipole amplitudes measured from each bolometer. At 100 and 143 GHz, the rms dispersions of the relative dipole calibration measured from individual bolometers are \(5 \times 10^{-6}\) and \(9 \times 10^{-6}\), respectively (see Fig. 13). Comparing with the rms variation of the FSL contribution to the dipole calibration listed in Table 1 (\(1 \times 10^{-4}\) and \(2 \times 10^{-5}\)) shows that corrections using the GRASP model are accurate to better than 5 and 2%, respectively, for 100 and 143 GHz. This is not surprising since the first order (spillover) dominates, as discussed earlier in this section.

\(^5\) Throughout this paper, we denote by \(\hat{C}_x\) (or \(\hat{D}_x\)) the undeconvolved power spectra, and \(\hat{C}_x\) (or \(\hat{D}_x\)) the deconvolved power spectra.

2.5. ADC non-linearity systematic effects

Non-linearity in the ADCs\(^6\) in the bolometer readouts (Planck Collaboration VI 2014; Planck Collaboration VII 2016) introduces systematic errors in the data. Figure 5, for example, shows the deviations from linearity measured in a flight spare ADC. A perfectly linear device, in contrast, would lead to a horizontal line at zero. The strongest non-linearity in Fig. 5 at zero ADU, lies in the middle of the ADC range, and drives the main ADC non-linearity effect. ADC deviations from linearity are the dominant source of systematic errors in HFI low-\(\ell\) polarization data. They create a first-order variable gain for the readout electronics of each detector, as well as higher-order effects as described below.

In the 2013 data release, the effects of ADC non-linearities were partially corrected (during mapmaking) by application of a time-variable gain for each detector (i.e., calibration to astrophysics units; Planck Collaboration VI 2014), with residual effects at levels of a few percent or less in the TOI. This simplified approach to ADC non-linearity was adequate for the analysis of temperature anisotropies; however, it leaves residual effects in the polarization maps at the lowest multipoles at levels about 30 times higher than the noise.

In 2013, a proper correction that would take into account the detailed characteristics of the ADCs themselves at the TOI processing level was not possible because the pre-launch measurements of the ADCs had inadequate precision.

\(^6\) Space qualified 16 bits Successive Approximation Register type from Maxwell Technologies.
Planck Collaboration VII (2016). Accordingly, during the extended Planck observations with LFI, after the 3He for the 0.1-K cooler ran out (February 2012 to August 2013), we conducted an in-flight measurement campaign to characterize the HFI ADC non-linearities more accurately. The resulting model of ADC non-linearity was used to correct the 2015 HFI data (in TOI processing). Residual effects were much reduced, to a level of 0.2\textendash;0.3\% in the TOI, and had negligible effect on the 2015 polarization maps at multipoles $\ell \gtrsim 30$. No additional correction of the type made in 2013 was performed because it did not bring clear improvement. (This was subsequently understood to be a consequence of degeneracies with other corrections.) However, a better treatment of ADC non-linearities is required to achieve noise-limited polarization maps at multipoles less than 30.

The results in this paper are based on an improved treatment of ADC non-linearities, made possible by the new mapping code (Sro11), which simultaneously solves for temperature-to-polarization leakage and residual gain variations from ADC non-linearities. Specifically, the 2015 correction in the TOI (using the model of ADC non-linearity derived from the extended-mission measurements) is followed by a step in Sro11 that calculates a multiplicative gain correction of the residuals left by the first step.

In this section, we explain why application of a time-variable gain worked reasonably well for temperature in 2013, why a model of ADC non-linearity worked well enough for high-$\ell$ polarization in 2015, and why a global determination of leakage levels, together with the residual gain variations induced by the ADC non-linearity, works better yet, and can be used in this paper for low-$\ell$ polarization. In addition, we show that a higher-order (but non-negligible) of ADC non-linearity acting on the CMB dipole also has to be taken into account.

To begin, consider how the signal levels at the inputs of the ADCs change with time. Figure 6 shows the fast-sampled signal from a single bolometer (143-1a) for three different time periods. The left panel shows the 80 fast samples in one cycle of the 90-Hz square-wave modulation of the bias current across the bolometer. Because of the square-wave modulation, the first and last sets of 40 samples are nearly mirror images of one another across the x-axis. The units are raw analogue-to-digital units (ADU). Middle: normalized histogram of the fast-sample signal values for day 91 of the mission, in ADU. The signal spread is dominated by the combination of the noise and the square-wave modulation of the bias current across the bolometer (left panel), with additional contributions from the CMB solar dipole. Right: normalized histograms for each day, starting with day 91, stacked left to right for the entire mission. Histogram values are given by colour, as indicated. The obvious symmetric trends during the mission are caused by drifts in temperature of the bolometer plate. Isolated days with large deviations from zero, seen as narrow black vertical lines, are due to solar flares.

Fig. 6. Fast-sampled signal from bolometer 143-1a. Left: eighty samples from early in the mission, corresponding to one cycle of the 90-Hz square-wave modulation of the bias current across the bolometer. Because of the square-wave modulation, the first and last sets of 40 samples are nearly mirror images of one another across the x-axis. The units are raw analogue-to-digital units (ADU). Middle: normalized histogram of the fast-sample signal values for day 91 of the mission, in ADU. The signal spread is dominated by the combination of the noise and the square-wave modulation of the bias current across the bolometer (left panel), with additional contributions from the CMB solar dipole. Right: normalized histograms for each day, starting with day 91, stacked left to right for the entire mission. Histogram values are given by colour, as indicated. The obvious symmetric trends during the mission are caused by drifts in temperature of the bolometer plate. Isolated days with large deviations from zero, seen as narrow black vertical lines, are due to solar flares.
Clearly the ADC non-linearity correction performed in the 2015 analysis is a big improvement over the variable-gain adjustment used in the 2013 results. Nevertheless, the residual errors from the non-linearity correction alone are still too large for accurate polarization measurements at low multipoles (Planck Collaboration VIII 2016). However, correction of these residual errors with a residual gain adjustment is now possible in the Srollo11 mapmaking, which solves simultaneously for temperature-to-polarization leakage levels and gain variations, something that was not possible in the previous mapmaking algorithm. The implementation of this approach is described in the following sub-section.

2.6. Correction of temperature-to-polarization leakage

Once the HPRs are built with far sidelobes and zodiacal emission removed, 6% of the HPRs are discarded using the criteria described in Planck Collaboration VII (2016). Using a generalized destripper, which takes advantage of the redundancies in the scanning strategy, we solve self-consistently for all temperature-to-polarization leakage terms:

- ADC non-linearity-induced gain variation;
- additional empirical complex transfer functions;
- calibration factors;
- bandpass mismatch coefficients associated with foregrounds.

The destripper baseline solution avoids regions of the sky with strong gradients that could bias the baselines. We construct one sky mask per frequency using a threshold in temperature (Sect. B.2). The foreground templates for the bandpass mismatch leakage are the Commander dust, CO, and free-free maps (Planck Collaboration IX 2016). The detailed description of the method, performance from simulations, and tests are to be found in Appendix B.

2.6.1. ADC-induced gain correction

A less biased measure of gain changes is given in Fig. 8, which shows differences in dipole amplitudes measured on the same ring one year apart. Application of the ADC non-linearity model to the TOI in the 2015 data release reduces the rms dipole amplitude variations from around 1% (no correction) to $2 \times 10^{-3}$ (blue curve). The red curve shows how well Srollo11 is able to solve for these residual gain adjustments, which are then applied. Algorithmic details and accuracies are described in Appendix B.

Distortions of the dipole shape caused by ADC non-linearities within each modulation state, however, are still not accounted for. Because the drift of the signal on the ADC is large between the two halves of the mission, half-mission null tests both in the data and in simulations give an excellent test of the quality of the ADC non-linearity corrections and of this residual dipole distortion. These are shown for 100 GHz in Fig. B.14 (see Sect. B.4.2 for details) and their associated EE power spectra in Fig. 9. These spectra are calculated for three cases: (i) simulated data from six realizations corrected with the ADC TOI correction alone (top panel, red lines); (ii) simulated data corrected with the additional correction of Srollo11 residual gain variation (bottom panel, red lines); and (iii) simulated data without any ADC non-linearity (i.e., the “ideal” case; both panels, green lines). In both panels, blue lines correspond to the data themselves processed in the same way.

The difference between the red lines in the top and bottom panels of Fig. 9 shows the efficiency of the Srollo11 residual gain approximation empirical reconstruction of the input signal at the level of the TOI.

The effects of ADC non-linearity on the dipole signal amplitude give an excellent measure of the gain, which can be applied linearly to all signals. We note that the distortion of the shape of the large-scale CMB anisotropies is negligible, but not the dipole distortion, which leaves non-negligible, additive, large-angular-scale residuals. Figure 7 shows a simulation that contains only the dipole signal and the thermal baseline drift throughout the mission, for four representative bolometers. The amplitude of the dipole signal in a given ring changes with the offset between the spin axis of Planck and the axis of the solar dipole. When the two are nearly aligned, the amplitude on a ring is small. When the two are far apart, the amplitude can reach $5^{-2}$ two are nearly aligned, the amplitude on a ring is small. When the spin axis of Planck the dipole signal in a given ring changes with the offset between the spin axis of Planck and the axis of the solar dipole. When the two are nearly aligned, the amplitude on a ring is small. When the two are far apart, the amplitude can reach $5^{-2}$

In 2015, the model of ADC non-linearities developed during the warm mission was applied to the TOI data (Planck Collaboration VII 2016). The correction takes into account the shape of the bolometer modulation (left panel of Fig. 6), and corrects for the ADC non-linearity induced by long-term drifts, resulting in residual effects in the maps an order of magnitude smaller than the 2013 correction, and good enough to be usable for high-$\ell$ polarization. However, the detailed shape of the dipole signal after passage through the bolometer readout circuits, and at the input of the ADC, is still not taken into account, leaving residuals in the data that are too large for low-$\ell$ polarization.

Figure 19 of Planck Collaboration VII (2016) shows the angular power spectra of difference maps, made with and without the ADC non-linearity correction, for individual bolometers at 100, 143, 217, and 353 GHz. Before the ADC non-linearity correction, errors caused by non-linearities scale approximately as $\ell^{-2}$ below multipoles $\ell \lesssim 100$. After correction, the power spectra are reduced in amplitude by factors of between 10 and 100 at low multipoles.
Fig. 8. Dipole amplitude difference on the rings observed twice, one year apart, for each of the 143-GHz polarization-sensitive bolometers. This detects the time-dependent response associated with the excursions of the signal on the ADC, illustrated in Fig. 7. The blue curve shows the dipole differences in units of $\mu K$ after ADC correction in the TOI processing, with no other processing. The red curve shows the measured dipole amplitude solved by Sroll, demonstrating the reliability of the model, which can then be applied to small signals.

Fig. 9. Power spectra of the 100-GHz half-mission null-test maps shown in Fig. B.14, which are dominated by ADC non-linearity effects. We compare six simulations at 100 GHz drawn from the Sroll uncertainties (red lines), and the average for the full frequency 100-GHz data (blue line). In the top panel only the TOI non-linearity correction is applied. In the bottom panel, both the TOI correction and the time-varying gain correction are applied. This leaves only the dipole distortion. For both panels the green lines are for simulations without the ADC non-linearity effect (only noise and other systematic residuals).

The difference between the red and green lines in the bottom panel shows the level of the residuals after this correction, which is dominated by dipole distortion. At $\ell \geq 4$, the red and green lines are at the same level within the noise plus small contributions from other systematic residuals. They all stay below $1 \times 10^{-3} \mu K^2$. The only significant deviations are for the quadrupole and octopole terms. Although this is the largest systematic effect left uncorrected in the HFI polarization maps, it is rather weak ($\leq 20\%$) compared to the expected $EE$ signal. This effect has been well-simulated, and the simulations will be used to remove it from the $EE$ power spectra in the science analysis.

2.6.2. Empirical complex transfer function

In the TOI processing, the time response of the bolometers and associated readout electronics is modelled as a Fourier filter, which is determined from observations of Saturn, Jupiter, and stacked glitches. The data are deconvolved from this response function (Planck Collaboration VII 2016). In addition, an in-scan, phase-shifted dipole caused by very long time constants (VLTC) is subtracted from the timeline, a necessary step for the convergence of the orbital dipole calibration, as described in Planck Collaboration VIII (2016). There are unavoidable uncertainties in the transfer function used to correct the timelines. We fit an additional empirical complex transfer function in the mapmaking, taking advantage of the redundancies in the data to capture any residuals from the above-mentioned bolometer/electronics time response deconvolution. The fit also captures residuals from FSLs, which shift dipoles and low frequency signals (in-scan and cross-scan).

The empirical transfer function is composed of four complex quantities associated with four spin frequency harmonics ($[0.017 \, \text{Hz}]$, $[0.033 \, \text{−} \, 0.050 \, \text{Hz}]$, $[0.067 \, \text{−} \, 0.167 \, \text{Hz}]$, and $[0.133 \, \text{−} \, 0.250 \, \text{Hz}]$), which are adjusted to minimize the residuals in the global mapmaking (see Appendix B.4.3). Including higher spin frequency harmonics provides only negligible improvements to the maps. In the four spin-harmonic frequency bands, the phase shifts of the transfer functions are easily fitted because they are not degenerate with the sky signal. However, for $100 \, \text{−} \, 217 \, \text{GHz}$, the CMB + foreground signals are too weak to fix the amplitudes of the transfer functions accurately and no amplitude correction is applied.

Figure 10 shows this transfer function for the eight PSBs at 353 GHz, where the strong Galactic dust signal allows an
accurate determination. The real part of the function measures the asymmetry between the cross-scan and the in-scan residuals. The imaginary part measures the shift along the scan. At 353 GHz, the imaginary part is almost negligible.

To estimate the accuracy of the empirical transfer function, we use odd-minus-even Survey map differences, which are sensitive to phase shifts at low harmonics of the spin frequency. We compute a pattern map associated with a phase shift of signal. The correlation of the data with this pattern gives the residual error left in the signal after correction with the empirical transfer function. These relative errors on the signal are shown in Fig. 11. Comparing the residual errors at the four lowest sets of multipoles to those at higher multipoles, we see only upper limits below $10^{-3}$ at 100 and 143 GHz, and three times lower at 217 and 353 GHz. This clearly demonstrates that the additional complex transfer function works well to correct phase shift residuals at the low multipoles that have been fitted. The map-making does not include corrections for temporal frequencies higher than 0.250 Hz, corresponding roughly to $\ell > 15$, and the odd–even Survey difference test still detects some shifts in the data.

Transfer function residuals also induce leakage of the Solar dipole into the orbital dipole. This leakage affects calibration differently in odd and even surveys. The solar dipole residual amplitudes per detector with respect to the average per frequency are displayed in Fig. 12. The residual amplitude provides a strong test of the improvement provided by the transfer function correction in reducing the leakage between dipoles and gain differences between odd and even Surveys. At CMB frequencies (100 and 143 GHz), this figure does not show any systematic odd/even Survey behaviour at the level of $0.250\text{ Hz}$, corresponding roughly to $\ell > 15$, and the odd–even Survey difference test still detects some shifts in the data.

Solar calibration uncertainties (as determined from the fitting procedure; Appendix B.4.3) to the maps and power spectra using the E2E simulations. The auto-power spectra (Fig. B.16) show that over the reionization peak the residuals are at a very low

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**Fig. 10.** Best-fit solutions for the real and imaginary parts of the empirical additional transfer function as a function of frequency, for the 353-GHz bolometers.

**Fig. 11.** Ratio of the fitted data to simulated patterns detecting the residual imaginary part of the empirical transfer function, measured in odd minus even Survey difference maps averaged for sets of harmonics. The transfer function correction has been applied only over the four first sets of harmonic ranges ($\ell < 15$); higher harmonics have not been corrected by the empirical transfer function.

**Fig. 12.** Residual solar dipole amplitude for each bolometer, by Survey. The average dipole at each frequency is subtracted. For 100 and 143 GHz (top panels), the variations are compatible with the relative calibration uncertainty of $10^{-4}$. At 353 GHz, the scale is expanded by a factor of five, and all detectors show an obvious odd/even pattern, which is marginally apparent at 217 GHz.
Fig. 13. Relative calibration measured by the dipole amplitude for each polarization-sensitive detector with respect to the mean dipole across a frequency band.

Fig. 14. Comparison of the response of each detector to dust as measured on the ground (blue) and as solved by SRo11 (red).

2.6.4. Tests of bandpass mismatch leakage coefficients on gain: comparisons with ground tests

The SRo11 mapmaking procedure (Appendix B) solves for temperature-to-polarization leakage resulting from the different response that each bolometer has to a foreground with an SED different from that of the CMB anisotropies. The solved bandpass mismatch coefficient associated with thermal dust emission is compared in Fig. 14 to that expected from pre-launch measurements of the detector bandpass (Planck Collaboration IX 2014). The statistical uncertainties on the ground measurements are dominated by systematic effects in the measurements. For all bolometers except 143-3b, the two are consistent to within the error bars estimated using simulations. The smaller error bars are the sky determinations by SRo11 and are in closer agreement with ground measurements than the conservative estimates of the systematic errors on the ground measurements would predict. The only exception is bolometer 3b, for which the ground and sky measurements differ by nearly $3\times$ the more accurate sky uncertainty.

2.6.5. Summary of improvements

The generalized destriper solution, solving simultaneously for bandpass-mismatch leakage, intercalibration errors, and ADC-induced gain variations and dipole distortions, has been shown to be necessary to achieve a nearly complete correction of the ADC non-linearities. This leads to much improved maps at low multipoles compared to previous releases. In Sect. 6.2 and Appendix B we will demonstrate that SRo11 mapmaking does not filter or affect the CMB signal itself.

At 100, 143, and 217 GHz, we are now close to being noise-limited on all angular scales, with small remaining systematic errors due to the empirical ADC corrections at the mapmaking level. These separate corrections should be integrated in the TOI/HPR processing for better correction. At 353 GHz, and to a lesser extent 217 GHz, we observe residual systematic calibration effects, as seen in Figs. 12 and 13, but we will show in the following sections that the residuals are small enough to have negligible effect on the determination of $\tau$. The origin of

level: $D(\ell) < 10^{-4}\mu K^2$ for CMB channels$^8$; and $D(\ell) \approx 10^{-3}\mu K^2$ for 353 GHz, except at $\ell = 2$, where it reaches $10^{-2}\mu K^2$. This demonstrates that the residuals of these systematic effects have a negligible effect on $\tau$ measurements, except possibly at $\ell = 2$.

2.6.3. Inter-detector calibration of the polarization-sensitive bolometers

Calibration mismatches between detectors produce leakage of temperature to polarization. The inter-detector relative calibration of the PSBs within a frequency band can be tested on single-detector, temperature-only maps (the polarized signal of the full-frequency map is subtracted from the detector TOI). The best-fit solar dipole (determined from the 100 and 143-GHz full-frequency maps) is removed. The residual dipoles in the maps measure the relative calibration of each detector with respect to the average over the frequency band. The results are shown in Fig. 13.

The low level of variations constrain the residual calibration mismatch between detectors that could lead to leakage of temperature to polarization. The relative calibration factors averaged over the full mission show rms dispersions of $\pm 5 \times 10^{-5}$ for 100 GHz, $9 \times 10^{-5}$ for 143 GHz, $2 \times 10^{-3}$ for 217 GHz, and $2 \times 10^{-4}$ for 353 GHz. At 100 GHz, 143 GHz, and 217 GHz, these dispersions are very small, and unprecedented for a CMB experiment. Absolute calibrations of band averages are discussed in Sect. 5.1. At CMB frequencies, results are still affected by gain errors between bands and by residual gain variations over time. At these frequencies, the gain mismatch is consistent with statistical errors (Tristram et al. 2011), therefore, it is not possible to improve the gain mismatch any further at these frequencies. At 353 GHz, the gain mismatch is larger than the statistical errors. The worst outliers (bolometers 353-6a and 353-6b) also show large odd -- even discrepancies in Fig. 11. Therefore there is hope for improving the relative calibration.

$^8$ Throughout this paper, we call CMB channels the 100, 143, and 217 GHz channels.

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this effect is not fully understood; correction algorithms are in development.

3. Consistency tests of the HFI polarization maps

As described above and in Appendix B, the SRo11 mapmaking algorithm corrects simultaneously for several sources of temperature-to-polarization leakage that were not previously corrected.

Section 3.2 gives the results of null tests that show how systematic effects at large angular scales are very significantly reduced compared to those in the HFI polarization maps from the 2015 Planck data release. As a test of the accuracy of this process, the results are also compared with the HFI pre-2016 E2E simulations. We begin in the next sub-section (Sect. 3.1) by showing that detection of the a posteriori cross-correlations of the final maps with leakage templates cannot work because of the degeneracy with the dipole distortion.

3.1. Temperature-to-polarization leakage

As discussed in Sect. 2, any bandpass and calibration mismatch between bolometers induces temperature-to-polarization leakage, and hence spurious polarization signals. Each leakage pattern on the sky for each bolometer is fully determined by the scanning strategy, along with a set of leakage coefficients, and the temperature maps involved (dipole and foregrounds). The SRo11 approach improves on the 2013 and 2015 HFI map-making pipeline by correcting all temperature-to-polarization mismatches to levels where they are negligible. Detector inter-calibration has been much improved, as shown in Sect. 2.6.3. Similarly the residual bandpass leakage (mainly due to dust and CO) in the $Q$ and $U$ HFI pre-2016 maps is also greatly reduced (Appendix B.4.1).

In the 2015 data release, we used leakage template fitting (Planck Collaboration VIII 2016) to check a posteriori the level of temperature-to-polarization leakage residuals, although this leakage was not removed from the maps. From Sect. 2.6 and the appendices, we expect temperature-to-polarization leakage to be very much reduced for the HFI pre-2016 data set. Contrary to expectations, however, the template-fitting test (expanded to account for synchrotron polarized emission) on the HFI pre-2016 release used in this paper still reveals significant leakage. Suspecting that the problem is residual dipole distortion induced by ADC non-linearity, which is not yet removed, we performed leakage tests on simulations both with and without the effect. This is done by forcing the gain to be constant within a pointing period, which removes only the dipole distortion within the ADC non-linearity effects.

Figure 15 shows that auto-spectra exhibit a leakage in the pre-2016 100-GHz data (green line), comparable to the simulations with (blue line) full ADC non-linearity effects. The red line, with the ADC dipole distortion effect removed, is lower by a factor of 5 or more. This demonstrates that the detected leakage at 100 GHz contains a potentially significant, and possibly dominant, spurious detection due to a degeneracy between the dipole distortion and the leakage templates. This is in line with the low level of the leakage and the level of the dipole distortion discussed in Sect. 2.5. This can only be confirmed through E2E simulations and comparison with data residuals from an appropriate null test. The remaining systematic effects are at a level of $8 \times 10^{-3} \mu K^2$ for $\ell > 3$. The quadrupole systematic term is an order of magnitude larger. As discussed before, quadrupole and octopole systematic effects dominate in Fig. 9. The residuals of the ADC non-linearity dipole distortion at $\ell > 3$ are small with respect to the $F$-$EE$ signal.

Figure 16 shows results for 100, 143, and 217-GHz data. All spectra show a rise similar to the one seen for the blue line in Fig. 15, which simulates the ADC non-linearity dipole distortion at 100 GHz. The higher frequencies also exhibit negligible temperature-to-polarization leakage, but have comparable ADC non-linearity dipole distortions. This is a strong indication that, at these frequencies, the dominant residual systematic is also due to ADC non-linearity acting on the dipole, which is not removed from the maps, in agreement with Fig. 17. This effect has to be accounted for in the likelihood before science results can be extracted from the pre-2016 maps. The temperature-to-polarization leakage is at a level of $10^{-3} \mu K^2$ or lower at $\ell > 4$. The dominant systematic at 353 GHz, in contrast, is calibration uncertainty (see Sect. 2.6.3).

3.2. Null tests

In this section we use null tests on power spectra, together with our understanding of the simulated systematic effects discussed in Appendix B, to demonstrate that we have identified all detectable systematic effects. In Fig. 17, the green lines show the total of noise and systematic effects. Noise (red lines) dominates at multipoles $\ell > 10$ for all frequencies. For the CMB channels (100, 143, and 217 GHz) the main systematic is the ADC-non-linearity dipole distortion (purple lines), which is not removed in the mapmaking; for this systematic, it is not the residual but the effect itself that remains in the maps. The residuals from other effects of ADC non-linearities are smaller (dark blue lines), and the bandpass leakage residual (light blue) is smaller still. Frequency-band intercalibration residuals (orange) are even lower, as are other systematic effects that are not shown.
For the 353-GHz channel, which is used only to clean foreground dust, the simulated systematic effects at low multipoles are all negligible with respect to the F-EE model level scaled by the foreground correction coefficients for 100 and 143 GHz (dashed and dotted black). Although the inter-survey calibration difference shown in Fig. 12 is greater for 353 GHz than for the CMB channels, this does not affect the present results.

We perform null tests on four different data splits. The first is the odd – even survey differences. These map differences test residuals associated with the scanning direction and far side lobes, short and long time constants in the bolometers, and beam asymmetry. The only clear evidence for any residual systematic effects associated with scanning direction is the odd – even solar dipole amplitude oscillation displayed in Fig. 12. This is above the noise level only at 353 GHz (Sects. 2.6.2 and 2.6.3). Other scanning-direction systematic effects are almost entirely eliminated by the SRoll mapmaking algorithm, and are not discussed further in this section.

The other three data splits used for null tests are by “detset” (Planck Collaboration VII 2016), by the first and second halves of each stable pointing period (Planck Collaboration VII 2016), and by the first and second halves of the mission (Planck Collaboration VIII 2016). In each case, we compute $C_\ell$ spectra of the difference between the maps made with the two subsets of the data. The spectra are rescaled to the full data set. The resulting spectra contain noise and systematic errors, and can be compared with the FFP8 simulations (Planck Collaboration XII 2016) of the Planck sky signal and TOI noise only.

Detset differences are sensitive to errors in detector parameters, including polarization angle, cross-polar leakage, detector-mismatch leakage, far side lobes, and time response.

Half-ring differences are sensitive to detector noise at levels predicted by the analysis of TOI (Sect. 2.3). All systematic errors cancel that are associated with different detector properties, drifts on timescales longer than 30 min, and leakage patterns associated with the scanning strategy.

Half-mission differences are sensitive to long-term time drifts, especially those related to the position of the signal on the ADC and related changes of the 4-K lines affecting the modulated signal.

The pre-2016 E2E simulations can be used to distinguish whether systematic effects are comparable to the level of the base $\Lambda$CDM $EE$ spectrum and could therefore affect the $\tau$ determination, or whether the systematic effects are negligible or accurately corrected by SRoll11.

Figure 18 compares $EE$ auto-spectra of detset, half-mission, and half-ring null-test difference maps for the pre-2016 data and the 2015 release data. The half-ring null test results (blue lines) agree with FFP8 as expected. For detset (red lines) and half mission (green lines) null tests, the 2015 data show large excesses over the FFP8 simulation up to $\ell = 100$. In contrast, the HFI pre-2016 data null test differences for 100 and 143 GHz are in good agreement with the FFP8 reference simulation. This is no surprise as systematics detected by this test have been shown to be small. At 217 GHz, the detset test is not yet at the level of FFP8.

For the half-mission null tests, the analysis of systematic effects shows that the ADC-non-linearity dipole distortion, which has not been removed, dominates, and should leave an observable excess at low multipoles in this test, which is not however seen. Thus this null test does not agree with the systematic analysis. A possible explanation is that the destriping is done on the full mission and applied to the two halves of the mission. The correlation thereby introduced in the two halves could lead to an underestimate of the residual seen in the null test. We checked this by constructing a set of maps in which the destriping is done independently for each half-mission. Figure 19 shows the results of this check. The independent destriper for the two half-missions (blue lines) shows a systematic effect at all frequencies in the half-mission null test that is not seen for the full mission minimization (red lines). The separated minimization can also be compared to the sum of all simulated effects (green lines); it shows the expected behaviour for the 100 to 217-GHz bands. We conclude that the uncorrected ADC-non-linearity dipole distortion accounts for most of the systematic detected by this new half-mission null test. This, of course, does not imply that the maps should be constructed using the separate half-mission minimizations because these use fewer redundancies than the full mission ones, and are therefore less powerful.

At 353 GHz, the null test is below the sum of all systematic effects between multipoles 2 and 50, and is not catching all systematic effects. The calibration and transfer functions for 353 GHz are not captured by the half-mission null test; this can plausibly explain the difference.

We have shown that the destriping of the two half-missions should be done independently in order to detect ADC non-linearity residuals. The 2016 data release will therefore include half-mission SRoll11 fits of parameters.

Figure 20 shows $EE$ and $BB$ spectra of the difference maps and cross-spectra (signal) over 43% of high latitude sky for both the 2015 HFI maps and for the HFI pre-2016 polarization maps described in this paper, and shows the relative improvements made by the SRoll11 processing. Differences between 2015 and 2016 are significant only at high multipoles.

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9 A small correlated noise component induced by the de-spiking procedure and the TTF corrections leads to non-white noise spectra (as in Fig. 1) different from the noise levels predicted from the TOI analysis (Planck Collaboration VII 2016; Planck Collaboration VIII 2016). The differences are significant only at high multipoles.
Fig. 17. Residual EE auto-power spectra of systematic effects from the HFI pre-2016 E2E simulations computed on 50% of the sky (colours specified in the top left panel apply to all panels). The purple line (ADC NL total residual) shows the sum of all effects associated with ADC non-linearity. The dark blue line (ADC NL no distortion) shows the level without the dominant dipole distortion. The plots show also the F-EE model (black curves). The 100-GHz and 143-GHz model scaled to 353 GHz with a dust SED is shown as dashed and dotted lines, respectively.

pre-2016 power spectra are not particularly sensitive to the polarization mask. The cross-spectra show the total signal level, dominated by polarized dust emission at ℓ ≤ 200 and, in EE, by the CMB at ℓ ≥ 200. This allows a direct comparison of the signal with noise plus systematic effects.

In Fig. 20, the 353-GHz detset null test for the 2015 data (blue line) at 3 ≤ ℓ ≤ 55 is 30 times larger than the FFP8 noise, and is at a level larger than 10% of the dust foreground spectrum. In the 2015 data release, systematic effects in the 353-GHz maps constitute the main uncertainty in the removal of dust emission from 100 and 143 GHz at low multipoles, dominating over statistical uncertainty in the dust removal coefficient (around 3%, see Sect. 5.2). In the pre-2016 data detset differences (green line), the systematic effects are much lower, but not yet at the TOI noise level.

In summary, all known systematic residuals have been seen in at least one null test at the expected level. Conversely, there is no excess over noise seen in a null test that is not accounted for by a known systematic. This important conclusion fulfills the goal of this section. However, one systematic effect has not been corrected at all, namely the ADC-induced dipole distortion because it requires a better ADC model that can be applied at the TOI or ring level simultaneously with the correction of other systematic effects. This will be done in the next generation of data.

4. LFI low-ℓ polarization characterization

The measurement of τ for the Planck 2015 release was based on the LFI 70-GHz maps, cleaned of synchrotron and dust emission with 30-GHz and 353-GHz templates, respectively (Planck Collaboration XIII 2016). In this paper we use the 70, 100, and 143-GHz polarization maps to calculate 70 × 100 and 70 × 143 cross-spectra (see Sect. 6). Since the LFI and HFI instruments are based on very different technologies, the systematic
effects they are subject to are largely independent. In particular, the dominant systematic effects in the two instruments (gain uncertainties for LFI and residual ADC effects for HFI) are not expected to be correlated. Therefore LFI × HFI cross-spectra provide a cross-check on the impact of certain systematic effects in the estimate of \( \tau \). There can be common mode systematics as well as chance correlations, however, so the cross-spectra cannot be assumed to be perfectly free of systematic effects.

In this analysis we use LFI data from the 2015 release. A detailed discussion of the systematic effects in those data is given in Planck Collaboration III (2016). To assess the suitability of the LFI data for low-\( \ell \) polarization analysis, we analyse residual systematic effects in two ways, first using our model of all known instrumental effects (the “instrument-based” approach; Planck Collaboration III 2016), and second using null maps of measured data as a representation of residual systematic effects (the “null-test-based” approach). In each case, we evaluate the impact of systematic effects on the extraction of \( \tau \) by propagating them through foreground removal, power spectrum estimation, and parameter extraction (Fig. 21). We then use our instrument-based simulations to support a cross-spectrum analysis between the LFI 70-GHz channel and the HFI 100- and 143-GHz channels. A summary of the effects that are most relevant for the present analysis is given in Appendix C.
Fig. 19. *EE* and *BB* cross-power spectra of the residual effect computed from null tests between half-mission maps based on full mission minimization (red curve) or independent minimization for each half mission (blue curve). This second approach clearly shows a systematic effect. The sum of all systematic effects, dominated by the ADC-non-linearity dipole distortion shown in green in Fig. 17, is at the same level as the simulated null test with independent minimization. The FFP8 power spectrum is given again for reference.
Fig. 20. $EE$ and $BB$ spectra of the 2015 maps and the pre-2016 maps used in this work at 100, 143, 217, and 353 GHz. The cross-spectra of detset and half-mission maps and the auto-spectra of the detset and half-mission difference maps are shown. The maps are masked so that 43% of the sky is used.
4.1. Instrument-based approach

Following Planck Collaboration III (2016), we produce a map of all systematic effects (the “systematics template”) at 70 GHz and add this to realizations of the full-mission noise and the CMB from FFP8. To quantify the impact of systematic effects in the foreground removal process, we use the corresponding systematic effects templates at 30 GHz and 353 GHz, and scale them to 70 GHz with spectral indexes $\alpha_{30/70} = 0.063$ and $\beta_{353/70} = 0.0077$ (Planck Collaboration XI 2016). This is equivalent to assuming that our cleaning procedure leaves no synchrotron or dust contamination in the final 70 GHz map, while we evaluate the impact of the rescaled noise and systematic effects. We then extract the power spectra for the temperature and polarization components at $\ell < 30$. The spectra are calculated over the same sky region used to derive $\tau$ in Planck Collaboration XI (2016).

To calculate the bias introduced by systematic effects on $\tau$, $r$, and $\log(A_s)$, we compare 1000 FFP8 realizations of the polarized CMB (for a fiducial value $\tau = 0.065$), plus white and $1/f$ noise including systematic effects, with 1000 similar simulations containing only CMB and noise. For each realization, we calculate the marginalized distributions for each of the three parameters $X$ ($=\tau$, $r$, or $A_s$), and calculate the differences $\Delta X = X_{\text{syst.}} - X_{\text{no syst.}}$, which represent the bias introduced in the estimates of parameter $X$ by the combination of all systematic effects.

4.2. Null-test-based approach

The above analysis only probes systematic effects that are known a priori, and is limited by the accuracy of our instrument model. Furthermore, Fig. 23 shows that the amplitude of systematic residuals at large scales is comparable to the noise at 30 GHz, and somewhat lower than the noise at 70 GHz. Therefore tests are also needed that do not rely on a model for the systematic effects. For this purpose, we use null maps of measurement data as “templates” of the LFI systematic effects, add to them simulations with a set of realizations drawn from a cosmological model with $\tau = 0.05$ (all other parameters were fixed to the FFP8 values) and find no measurable difference from the previous case: $\langle \Delta \tau \rangle = 0.005$.

For the optical depth, we find a mean bias $\langle \Delta \tau \rangle = 0.005$ (Fig. 22), or approximately 0.25 times the standard deviation of the value of $\tau$ measured by LFI (Planck Collaboration XIII 2016). The positive measured bias may suggest a slight overestimate of the measured value of $\tau$ caused by systematics. We also tested the sensitivity of the measured bias with the fiducial value of $\tau$. We repeated the analysis replacing the FFP8 CMB simulations with a set of realizations drawn from a cosmological model with $\tau = 0.05$ (all other parameters were fixed to the FFP8 values) and find no measurable difference from the previous case: $\langle \Delta \tau \rangle = 0.005$.

In the above analysis, the values of the scaling coefficients $\alpha_{30/70}$ and $\beta_{353/70}$ were fixed at the values measured in the real data, as appropriate in quantifying the impact of residual systematic effects in the released LFI maps and likelihood. For a more general assessment of the component-separation and parameter-estimation procedures in the presence of systematic effects, these quantities should be re-estimated for each individual realization (e.g., Sect. 2.5 of Planck Collaboration XIII 2016).
null maps. Figure 24 shows results for the 70-GHz channel. At $\ell < 15$, the full-mission spectrum is higher on average by a factor of about 2.5 than the spectra of the difference maps, likely due to partial cancellation of common modes. However, the comparison indicates a reasonable consistency of the amplitudes of the three power spectra, within the observed scatter, at a level $\approx 10^{-3}$ for $\ell > 2$. This indicates that applying the null-test-based approach to the real data provides a useful test of LFI data quality.

Next, we compute the power spectra for the full mission and for the half-mission differences using the measurement data. Residuals in year-map differences (e.g., year 1 − year 2) are more consistent with noise than residuals in Survey differences, as expected from the increased efficiency of the destriping algorithm (Planck Collaboration VI 2016); however, we find only marginal improvement when using 2-year map differences compared to combinations of single-year maps. Thus we adopt the latter, which allows us to evaluate the two half-mission combinations

$$D_{12-34} \equiv \frac{(yr1 + yr2) - (yr3 + yr4)}{w8}, \quad (1)$$

$$D_{24-13} \equiv \frac{(yr2 + yr4) - (yr1 + yr3)}{w8}, \quad (2)$$

where

$$w8 = \sqrt{N_{\text{hits}} \times \left( \frac{1}{N_{\text{hits}}^{yr1}} + \frac{1}{N_{\text{hits}}^{yr2}} + \frac{1}{N_{\text{hits}}^{yr3}} + \frac{1}{N_{\text{hits}}^{yr4}} \right)} \quad (3)$$

is a weight based on the number of hits per pixel, $N_{\text{hits}}$, needed to equalize the noise in the two maps. We apply the same mask used for extraction of $\tau$ in the instrument-based simulations. In order to correct for the mask mode-coupling and the polarization leakage effect we used CrossSpect, a MASTER-like (Hivon et al. 2002) power spectrum estimator.

Figure 25 shows the 70-GHz auto-spectra of the difference maps $D_{12-34}$ and $D_{24-13}$ using real data, after removal of the noise bias. For comparison, in the same figure we also show the same spectra of Fig. 24 from simulated systematic effects (we note the different scale). As expected, the scatter for the data is much larger than the scatter for the models of systematic effects. To verify whether the scatter observed in the data is consistent with instrument noise, we compute statistical error bars at each multipole from 1000 realizations of FFP8 noise. Over the multipole range $2 \leq \ell \leq 29$, we find reduced $\chi^2$ values of 0.94 for $D_{12-34}$ (PTE $= 0.55$), and 1.06 for $D_{24-13}$ (PTE $= 0.38$), accounting for $\ell$-to-$\ell$ correlations via the empirical noise $C_\ell$ covariance matrix. Considering only the lowest multipoles, $2 \leq \ell \leq 9$, we find reduced $\chi^2$ values of 0.61 (PTE $= 0.77$) and 1.25 (PTE $= 0.26$), respectively.
The fact that the scatter is consistent with FFP8 noise confirms that the amplitude of systematic effects, while not negligible, is smaller than white and 1/f noise, even at large scales. This level of systematic effects could still lead to small biases in the cosmological parameters, so we perform an analysis of the recovery of $\tau$ in the presence of systematic effects also for the null-test-based templates. Since these are based on a single realization of the real data, we cannot use the approach of Sect. 4.1 and marginalize over the CMB and noise realizations to obtain the average systematic impact on parameters. Rather, we proceed similarly to what was done in the above analysis of nullmap power spectra. We start by calculating the $D_{12-34}$ and $D_{24-13}$ yearly differences for the 30 and 70 GHz instrument-based systematic templates discussed above. We then generate two sets of 1000 CMB+noise and CMB+noise+simulated null maps, and analyse them as in the previous section. The resulting average bias on $\tau$ is $\approx 0.002$ and $\approx 0.003$, for the simulated $D_{12-34}$ and the $D_{24-13}$ combinations, respectively. In agreement with the power spectrum results of Fig. 24, we find that the null templates give rise to a lower bias than the full mission systematics templates.

We then add a single CMB realization to the null-test-based templates, and estimate parameters for these maps as well. Fig. 26 shows that the resulting estimates are well within the distributions. Note also that the bias in the case of $D_{12-34}$ is somewhat lower than in the case of $D_{24-13}$, consistent with the behaviour expected from simulations (Fig. 24). These results suggest that the instrument-based and null-test-based null maps have a consistent impact on power spectra and parameters, and provide support for the use of the instrument-based simulations in the cross-instrument analysis.

Figure 27 shows $EE$ and $BB$ pseudo-power-spectra from the 2015 LFI data release used in this paper, showing the difference maps and cross-spectra (signal) over 43% of the sky. Foregrounds are clearly visible in the cross-spectra only at $\ell < 30$ at 30 GHz and $\ell < 5$ at 70 GHz. As will be shown in Sect. 5.2, although the removal of the modest synchrotron foreground component at 70 GHz may not be extremely accurate, its final uncertainty is well within the noise.

5. Interfrequency calibration, component separation, and power spectra

The low-multipole polarization signals measured by Planck include Galactic foregrounds. In this section, we describe the combination of Planck frequency bands that we use to separate the CMB signal from these foregrounds. First we revisit dipole residuals in the single-frequency maps to establish the level of precision of the inter-calibration error between the frequency bands of Planck in both instruments. Then, we use the SMICA component-separation code to show that the polarization signal at large angular scales consists mostly of CMB and two Galactic foreground components. A third component does not improve the fit, and we show that a simple internal linear combination (ILC) method is sufficient to clean the CMB-dominated bands by regressing synchrotron with 30 GHz and dust with 353 GHz. Finally, we describe the angular power spectra at low multipoles using two estimators and subtracting the foreground components.
Fig. 27. $EE$ and $BB$ differences and cross-spectra of the 2015 maps at 30, 44, and 70 GHz, for different data splits. These maps are masked so that 43% of the sky is used. This figure shows similar plots to Fig. 20 for LFI frequencies.

5.1. Interfrequency calibration

For the 44, 70, 100, 143, 217, and 353 GHz channels, the photometric calibration is based on the “orbital dipole”, i.e., the modulation of the solar dipole induced by the orbital motion of the satellite around the solar system barycentre (see details in Appendix B). The “solar dipole”, induced by the motion of the solar system barycentre with respect to the CMB, is stronger by an order of magnitude, and can be measured after masking the Galactic plane and removing foreground emission outside the mask. If the uncertainties associated with foreground removal are negligible, the amplitude of the solar dipole provides an excellent check on the relative calibration between different frequencies.

Most of the higher-order terms discussed in Notari & Quartin (2015) affect all CMB dipoles in the same way, and thus do not induce errors in the relative calibration of the solar dipole with respect to the orbital one but can contribute small factors to the frequency calibration differences.

The frequency-dependent kinematic-dipole-induced second-order quadrupole and dipole from foreground monopoles (Kamionkowski & Knox 2003) have amplitude $2.0 \times 10^{-4} \mu K$ at 100 GHz, $3.9 \times 10^{-4} \mu K$ at 143 GHz, $8.2 \times 10^{-4} \mu K$ at 217 GHz,
and $1.7 \times 10^{-3} \mu K$ at 353 GHz. These corrections have a negligible impact on the calibration of the CMB channels.

Table 2 summarizes the HFI measurements of the solar dipole from 100 to 353 GHz. At 100 GHz, the direction and amplitude of the solar dipole remain within two standard deviations as the sky fraction changes from 37% to 58%. At 143 GHz, the amplitude of the solar dipole remains within two standard deviations dipole from 100 to 353 GHz. At 100 GHz, the direction and amplitude calibration based on measurement of the first two peaks (specifically, over $110 \leq \ell \leq 500$) of the CMB power spectrum, is very close to that determined from the solar dipole. The difference in calibration between the solar dipole and the first two CMB peaks gives an upper limit on the residual function error relative to 100 GHz, between $\ell = 1$ and $\ell \approx 300$, also shown in Table 3.

The 545-GHz channel is difficult to calibrate on the orbital dipole because the orbital dipole is so weak with respect to the dust emission. Instead, the 545-GHz channel was calibrated on Uranus and Neptune (Planck Collaboration VIII 2016). Nevertheless, the (much stronger) solar dipole and acoustic peak amplitudes can be compared with those of the CMB channels, once again after cleaning dust using the 857-GHz template. The result is that the planet calibrations agree with the CMB calibrations within 1.5% for 545 GHz. This implies that the 857 GHz is within 2.5% of the CMB calibration considering the uncertainty of their respective planet calibration. The absolute calibration uncertainty using planets was estimated at 5%, and is now shown to be within 2% of the photometric CMB calibration based on the orbital dipole and the COBE/FIRAS absolute calibration of the CMB temperature (Fixsen et al. 1997; Fixsen 2009). Since the Herschel observatory was calibrated with the same planet models, inter-calibration between Herschel and Planck is also at the 2% level (Bertincourt et al. 2016).

Table 2. Solar dipole amplitude and direction by frequency, as well as for the average (AVG) of the 100 and 143-GHz maps.

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>100 . . . . . . .</td>
<td>2</td>
<td>3361.25 ± 0.06</td>
<td>263.937 ± 0.002</td>
<td>48.2647 ± 0.0008</td>
</tr>
<tr>
<td>143 . . . . . . .</td>
<td>2</td>
<td>3362.85 ± 0.04</td>
<td>263.913 ± 0.001</td>
<td>48.2629 ± 0.0004</td>
</tr>
<tr>
<td>217 . . . . . . .</td>
<td>2</td>
<td>3366.56 ± 0.06</td>
<td>263.852 ± 0.002</td>
<td>48.2645 ± 0.0008</td>
</tr>
<tr>
<td>353 . . . . . . .</td>
<td>2</td>
<td>3364.19 ± 0.26</td>
<td>263.385 ± 0.009</td>
<td>48.3191 ± 0.0035</td>
</tr>
<tr>
<td>545 . . . . . . .</td>
<td>2</td>
<td>3398.72 ± 1.99</td>
<td>255.890 ± 0.070</td>
<td>48.1571 ± 0.0281</td>
</tr>
<tr>
<td>AVG . . . . . . .</td>
<td>2</td>
<td>3362.05 ± 0.04</td>
<td>263.925 ± 0.001</td>
<td>48.2641 ± 0.0004</td>
</tr>
</tbody>
</table>

Notes. Here dust emission is removed using the CMB-free 857-GHz map as a template. Fits are performed using three different masks based on the $I_{607}$ temperature, corresponding to 37%, 50%, and 58% of the sky. Uncertainties are purely statistical.

![Fig. 28. Relative calibration based on measurement of the first two acoustic peaks (blue) and on the solar dipole (red). The bottom panel is a zoom of the top panel. We use 100 GHz as the reference frequency for the dipole calibration method. In this plot, Planck 30-GHz and WMAP Q-band data may be affected by their relatively low angular resolution.](image_url)
Table 3. Relative calibration between the solar dipole and the first and second peaks ($\ell = 110$–500) in the CMB power spectrum with respect to 100 GHz.

<table>
<thead>
<tr>
<th>Frequency [GHz]</th>
<th>Solar dipole</th>
<th>First and second peaks</th>
<th>Transfer function $\Delta \ell = 2$–300</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Amplitude $[\mu K]$</td>
<td>$l$ [deg]</td>
<td>$b$ [deg]</td>
</tr>
<tr>
<td>44</td>
<td>...</td>
<td>...</td>
<td>...</td>
</tr>
<tr>
<td>70</td>
<td>...</td>
<td>...</td>
<td>...</td>
</tr>
<tr>
<td>94 (WMAP)</td>
<td>3355</td>
<td>...</td>
<td>...</td>
</tr>
<tr>
<td>100</td>
<td>3361.25</td>
<td>263.937</td>
<td>48.2647</td>
</tr>
<tr>
<td>143</td>
<td>3362.85</td>
<td>263.913</td>
<td>48.2629</td>
</tr>
<tr>
<td>217</td>
<td>3366.56</td>
<td>263.852</td>
<td>48.2645</td>
</tr>
<tr>
<td>353</td>
<td>3364.19</td>
<td>263.385</td>
<td>48.3191</td>
</tr>
</tbody>
</table>

Notes. The “Transfer function” in Col. 7 is the difference between the relative responses to the dipole and to the CMB first acoustic peak ($\ell = 2$–300).

In summary, absolute calibration of the 100-GHz channel on the orbital dipole is insensitive to sky fraction (and thus not affected by Galactic foreground removal). Based on that absolute calibration, we use the solar dipole to compare the calibration of the other Planck CMB channels and WMAP W-band. We also compare the calibration of the CMB channels using the CMB anisotropies in the multipole range 110–500. There is evidence of some potential orbital dipole calibration errors due to the dust foreground at frequencies above 100 GHz, but also of very stable behaviour of the transfer functions with Planck frequencies from 70 to 217 GHz. At 353 GHz, we still see a 0.3% discrepancy between various different calibrations, and for WMAP W band a 0.5% difference. Whether the origin of these discrepancies is in the calibration itself or is a result of transfer function errors cannot be determined by this analysis.

5.2. Diffuse component separation

In this section we discuss the effects of polarized diffuse component separation on the CMB spectrum (point sources can be ignored for low-multipole work). To begin, we use the (blind) SMICA code (Planck Collaboration XII 2014), with no assumptions about the number and properties of the foreground components, to establish the number and properties of the foreground components that must be removed, and the fraction of sky $f_{\text{sky}}$ to use. It turns out that two polarized foreground components are enough for polarization, i.e., including a third foreground component does not improve the fit. Not surprisingly, the two components are easily identified with dust and synchrotron emission. Changing $f_{\text{sky}}$ from 0.4 to 0.5 makes essentially no difference in the resulting CMB power spectrum, but changing to 0.6 or 0.7 makes a substantial difference. This leads us to adopt $f_{\text{sky}} = 0.5$.

The two likelihood methods described in Sect. 6 use internal linear combination (ILC) or template fitting to remove synchrotron and dust emission. The 30-GHz map is used as a template for synchrotron emission that is uncorrelated with dust, and the 353-GHz map is used as a template for dust emission. Table 4 shows the “projection coefficients” used by the different likelihoods. Table 4 also gives the SMICA projection coefficients for two blind components, and shows that the diffuse-component-separation procedure is very stable between the different approaches for 100 and 143 GHz. At 70 GHz, the dispersion is larger, but if no synchrotron component were explicitly removed, the synchrotron that is correlated with dust would still be taken care of; additionally, the uncorrelated part would have no effect to first order on the $100 \times 143$ GHz cross-spectra because the synchrotron signal is very weak at 143 GHz, as shown in Fig. 29.

Table 5 gives the average value of the power spectrum removed for each foreground at $\ell = 4$, at the peak of the $EE$ reionization feature, together with the associated uncertainties computed with the ILC method. The uncertainties are always lower than the $F$-$EE$ signal, by more than an order of magnitude. Figure 29 shows this graphically.

At the two Planck frequencies with the lowest noise, 100 and 143 GHz, the level of synchrotron emission is lower than that of dust by factors of 10 and 300, respectively. For 100 GHz, not removing the synchrotron would introduce a bias of less than 6% of $F$-$EE$. The 70-GHz spectrum is limited by noise rather than the large uncertainty (16%) in the synchrotron foreground removal, even though this is the largest foreground removal uncertainty in the Planck CMB channels for the reionization peak.
Planck Collaboration: Large-scale polarization and reionization

Table 4. Projection coefficients used by the two likelihood methods described in Sect. 6, as well as SMICA, for removal of dust and synchrotron emission using the 353- and 30-GHz maps, respectively.

| Frequency [GHz] | Dust | | | | | Synchrotron | | | |
|-----------------|------|------|------|------|------|-----------------|------|------|------|------|
|                 | Lollipop | SimBaL | SMICA | mean | error | Lollipop | SimBaL | SMICA | mean | error |
| 70 . . . . . .   | 0.0084 | 0.0060 | 0.0095 | 0.0080 | 16.7% | 0.0679 | 0.0520 | 0.0621 | 0.0621 | 16%   |
| 100 . . . . .    | 0.0193 | 0.0193 | 0.0183 | 0.0186 | 4.4%  | 0.0390 | 0.0200 | 0.0210 | 0.0267 | 20%   |
| 143 . . . . .    | 0.0399 | 0.0427 | 0.0399 | 0.0408 | 2.3%  | 0.0199 | 0.0076 | 0.0080 | 0.0118 | 45%   |

Notes. In all these cases, $f_{sky} = 0.5$.

Table 5. For each CMB frequency, the amplitude of the power spectrum $D_\ell$ at $\ell = 4$ that is removed for the dust and synchrotron foregrounds.

| Frequency [GHz] | Dust | | | | | Synchrotron | | | |
|-----------------|------|------|------|------|------|-----------------|------|------|------|------|
|                 | Mean | Uncertainty | | | | Mean | Uncertainty | | | |
| 70 . . . . . .   | 0.0041 | 0.0010 | 0.019 | 0.005 | | | | | | |
| 100 . . . . .    | 0.0227 | 0.0020 | 0.0036 | 0.0011 | | | | | | |
| 143 . . . . .    | 0.106 | 0.0052 | 0.0007 | 0.0004 | | | | | | |

Notes. These are computed from the 353 and 30-GHz power spectra at $\ell = 4$; uncertainties are scaled appropriately by the projection coefficients and relative errors.

The spatial variation of the dust spectral energy distribution at high latitude has been analysed on 400 deg$^2$ patches, and is smaller than the ILC uncertainty (Planck Collaboration Int. XXX 2016).

Figure 30 shows the level of residual foregrounds. It is clear that the component-separation errors propagated to the power spectra are much lower than the sum of all systematic effects, and have a negligible impact on the determination of $\tau$.

5.3. Power spectra

Likelihood analyses for CMB cosmological parameters were originally developed for CMB experiments that were dominated by CMB signal and detector noise, in contrast to more recent experiments with much lower noise in which residuals from instrumental systematic effects and foreground subtraction dominate over the detector noise, especially at low multipoles. Such analysis approaches rely on pixel-pixel covariance matrices coming from a large number of simulations of CMB and noise, which are assumed to be two statistically independent Gaussian fields for the purposes of these likelihood codes. Pixel-based likelihoods can also account for noise correlations and masking of the sky. In the Planck likelihoods, the “noise” description combines the detector and readout chain white noise, some correlated fraction due to 1/f noise, and residuals of systematic effects that have statistical properties that are not well understood. These systematic effect residuals thus need to be brought to levels much lower than the Gaussian noise.

5.3.1. Cross-spectra at very low multipoles

Figure 9 shows that systematic effects in the 100-GHz channel are below $10^{-3} \mu K^2$ for $4 < \ell < 100$. At $\ell = 2$ and 3, the ADC-induced dipole distortion dominates the systematic effects in simulated auto-spectra (Fig. 17). Figure 31 shows that the total level of simulated systematic effects (purple line) in the $100 \times 143$ cross-spectrum is significantly reduced compared to the auto-spectra of both frequencies (Fig. 17) for most multipoles relevant for the reionization feature. In the first two columns of Table 6 we give $(D\ell)_{\text{rms}}$ for $2 \leq \ell \leq 8$ for the auto-spectrum of the ADC-induced dipole distortion and noise from simulations (Fig. 17). The third column gives the same $(D\ell)_{\text{rms}}$ for the simulated ADC induced dipole distortion EE cross-spectrum $100 \times 143$ (Fig. 31) tracing the final residuals. The fourth column gives this same quantity for the BB data cross-spectrum (bottom panel of Fig. 33) for noise and residual systematics after removal of the average of the simulation of systematic effects (where the expected signal is very small) for QML2.

The steps in the reduction of the ADC residuals from the simulation auto-spectra ($9 \times 10^{-3}$ and $13 \times 10^{-3} \mu K^2$) to the cross-power spectrum ($6 \times 10^{-3} \mu K^2$) and finally the QML BB data cross-spectrum of residual systematics and noise ($3 \times 10^{-3} \mu K^2$) lead us to only a small excess with respect to the expected noise ($3.0 \times 10^{-3}$ to $2.0 \times 10^{-3} \mu K^2$).

Cross-spectra calculated from two different detsets within a single frequency, for both 100 and 143 GHz, have a higher level of residual systematics than those from cross-frequency detsets,
as discussed below. As explored in Sect. 5.2, 100 × 143 EE cross-spectra can be cleaned of dust and of the correlated synchrotron fraction (60%) with the 353-GHz template, and have negligible synchrotron power remaining because synchrotron emission is so weak at 143 GHz. We also described in Sect. 5.2 why we adopted fsky = 0.5. For these reasons, we choose the full frequency 100 × 143 cross-spectra and fsky = 0.5 as our baseline.

5.3.2. Estimators

We use both pseudo-Cℓ (PCL) and quadratic maximum likelihood (QML) estimators to extract cross-spectra from maps. Two versions of the PCL cross-spectra were produced, using Xpol (Tristram et al. 2005) and Spice, a MASTEr-like code (Hivon et al. 2002).

QML estimators have been widely discussed in the literature (e.g., Tegmark 1996; Bond et al. 1998; Efstathiou 2004, 2006). QML auto-spectra are close to optimal, but must be corrected for noise bias. The removal of this bias requires an accurate estimate of the pixel noise covariance matrix N_ip. In analogy with QML auto-spectra, it is straightforward to define a quadratic cross-spectrum estimator that is unbiased. The resulting cross-spectrum estimator will not have minimum variance, but nevertheless we retain the nomenclature “QML” to distinguish it from the PCL estimators described above.

For two maps “a” and “b,” the cross-spectrum estimate is defined as

\[ y_{\ell r}^{ab} = x_i^a x_j^b E_{\ell r}^{ij} , \]

where i and j are pixel numbers, and \( \ell \) and r form a paired index with \( \ell \) denoting multipole number and r denoting spectrum type (e.g., TT, TE, EE or BB). The matrix E here is

\[ E_{\ell r}^{ij} = \frac{1}{2} (C_i^{\ell})^{-1} \frac{\partial C}{\partial C_{\ell r}} (C_j^{\ell})^{-1} , \]

where the covariance matrix \( C = S + N \) and \( \tilde{C} \) is a “reshaped” covariance matrix of the form

\[ \tilde{C} = \begin{pmatrix} C_{TT} & 0 & 0 \\ 0 & C_{QQ} & C_{QU} \\ 0 & C_{UQ} & C_{UU} \end{pmatrix} , \]

that does not mix temperature estimates with polarization estimates. Provided that the noise between maps \( a \) and \( b \) is uncorrelated, the expectation value of Eq. (4) is

\[ \langle y_{\ell r} \rangle = \tilde{E}_{\ell r}^{ij} C_{\ell r} , \]

where

\[ \tilde{E}_{\ell r}^{ij} = \frac{1}{2} \text{Tr} \left[ \frac{\partial C}{\partial C_{\ell r}} (C_i^{\ell})^{-1} \frac{\partial C}{\partial C_{\ell r}} (C_j^{\ell})^{-1} \right] . \]

Equation (7) can be inverted to give a deconvolved estimator of \( C_{\ell r} \). The variance of the cross-spectrum estimator can be written in terms of the matrices S, N, and E as

\[ \langle y_{\ell r}^{ab} y_{\ell r}^{ab} \rangle - \langle y_{\ell r}^{ab} \rangle \langle y_{\ell r}^{ab} \rangle = 2 S_{ip} S_{jq} + \langle N_{ip} + N_{ip} \rangle S_{jq} + N_{ip} N_{jq} E_{\ell r}^{ij} E_{\ell r}^{ij} . \]

Inaccurate determinations of the noise covariance matrices \( N^p \) will therefore not bias the power spectrum estimates, but will lead to inaccurate estimates of the variance, via Eq. (9).

In Sects. 2 and 3 we discussed systematic effects in full resolution maps. Most residual systematic effects are negligible above \( \ell = 50 \). For science analysis at \( \ell < 20 \), we degrade the resolution to HEALPix \( N_{\text{side}} = 16 \) with the following smoothing:

\[ f(\ell) = \begin{cases} 1 & \ell \leq N_{\text{side}} \\ \left( 1 + \cos \left( \frac{\ell - N_{\text{side}}}{2N_{\text{side}}} \right) \right) & N_{\text{side}} < \ell \leq 3 N_{\text{side}} \\ 0 & \ell > 3 N_{\text{side}} \end{cases} \]

This does not affect the analysis of systematic effects.
Fig. 32. $100 \times 143$ cross-spectra of noise and systematics from the average of HFPS1, HFPS2, and HFPS3 simulations, calculated using both PCL and QML estimators (with the covariance matrix from HFPS2). Theoretical spectra are plotted (in black) for $\tau = 0.05, 0.07, 0.09$. 

5.3.3. Bias estimate

To estimate the bias induced by residual systematic effects at the power spectrum level, we average simulations HFPS1, HFPS2, and HFPS3 (Sect. 2.2) and calculate cross-spectra on the average data with both estimators (Fig. 32). These averages are then removed from the data. We note that the biases and their uncertainties are relatively small compared to the theoretical spectra shown in Fig. 17. This is due to the use of cross-spectra, as mentioned above.

5.3.4. Building the cross-spectra

For QML estimators, full mission pixel-pixel noise covariance matrices at $N_{\text{side}} = 16$ were produced from the 2015 FFP8 simulations, which capture some aspects of correlations via pixel hit counts and the Planck scanning pattern, but which do not include errors from instrumental systematic effects. To account for instrumental systematic effects, a covariance matrix is derived from the HFPSs. The signal covariance matrix assumes the 2015 base $\Lambda$CDM model parameters with $\tau = 0.07$. After adding CMB signal, this matrix can be inverted. We used the HFPS1 (83 realizations) and HFPS2 (100 realizations) simulations. One set is used to build the pixel covariance matrix. We compute the QML spectra using either the same set or the other one, to test the effect of overfitting and noise bias introduced by using the same set when the number of simulations is small. These biases decrease as the number of simulations increases. As an extra check, we swap the two independent sets and find fully compatible results.

The $100 \times 143$ cross-spectra for science analysis are displayed in Fig. 33. Debiasing is shown for the SimBaL pseudo-$C_\ell$ spectra, and is significant only at very low multipoles. The debiased Xpol and SimBaL PCL spectra are fully consistent.

The QML power spectra calculated from HFPS1 and HFPS2 differ only slightly. A quantitative estimate of the implications when propagated all the way to $\tau$ is given in Appendix D. The BB power spectra from both codes show negligible signal, as expected, and can be used as an estimate of the noise and an upper limit on residual bias.

The QML estimator produces more local estimates, i.e., with less covariance between multipoles, and better isolation of E- and B-modes. The latter is clearly seen in Fig. 33. We also expect the QML approach to give more optimal estimates than the PCL approach, and indeed the QML error bars are found to be significantly smaller than the PCL ones. In both cases, the impact

Fig. 33. $100 \times 143$ cross-spectra used in this paper. Top: debiased Xpol PCL (green), and the biased (red) and debiased (blue) SimBaL PCL spectra. Middle: QML power spectra (red biased, blue debiased) for HFPS1. Bottom: same for HFPS2. Model spectra for $\tau = 0.050, 0.070,$ and 0.090 are displayed in black (dashed) lines.
of debiasing the spectra for the ADC non-linearity distortion is small compared to the uncertainties.

Figure 34 compares statistical distributions of expected values of the \(EE\) cross-spectra derived from the HFPs to observed values (vertical lines), and gives the associated probability-to-exceed (PTE) those values. For \(2 \leq \ell \leq 5\), we see non-Gaussian and asymmetrical probability distributions coming from systematic residuals and cosmic variance. Figure 35 shows the PTE expressed as the equivalent \(\chi^2\) of a Gaussian distribution, for a broader range of multipoles. The PCL and QML estimators are largely in agreement. There is a significant outliers: \(\ell = 16\) which is bad for both estimators. The PTEs are similar, demonstrating that the results from both procedures are in agreement with the expected statistics. Since the QML estimate gives significantly smaller error bars (Fig. 34), we use it for the final results.

5.3.5. \(TE\) cross-spectra

The \(TE\) cross-correlation spectrum can in principle also contribute to the determination of \(\tau\), and has been used when the \(EE\) spectra were either too noisy (e.g., in early WMAP results) or limited by systematic effects (in earlier Planck data releases). Figure 36 shows that at present the \(TE\) spectrum is compatible with the range of \(\tau\) values allowed by \(EE\). Nevertheless the uncertainties are such that \(TE\) cannot bring any significant improvement to the determination of \(\tau\) from \(EE\), partly due to the large cosmic variance of the temperature signal at very low multipoles (see also Fig. 3 in Planck Collaboration Int. XLVII 2016). Furthermore, to include \(TE\) fully would require a more comprehensive analysis of component separation for the large-scale temperature map, which has not yet been done.

6. Likelihoods for \(\tau\)

6.1. Description of different likelihoods

In this section we estimate the reionization optical depth \(\tau\), using PCL and QML estimators of \(EE\) cross-spectra between the two best Planck channels, 100 and 143 GHz, at very low multipoles. The \(\tau\) parameter is strongly degenerate with the amplitude of the primordial spectrum \(A_s\). The \(TT\) power spectrum constrains the combination \(A_s e^{-2\tau}\) at the sub-percent level, \(10^9 A_s e^{-2\tau} = 1.875 \pm 0.014\) (Planck Collaboration XIII 2016). The \(\tau-A_s\) degeneracy can be broken using Planck \(TT\) data along with CMB lensing, or by combining with external data on large-scale structure, both of which constrain \(A_s\). However, the amplitude of the \(EE\) reionization feature depends quadratically on \(\tau\), with very little dependence on the other parameters of the \(\Lambda\)CDM model. A 10% constraint on \(\tau\) from \(EE\) data constrains \(A_s\) at the 1% level (\(\delta A_s/A_s \approx 2.0\) \(\tau \approx 0.06\)), and can affect some of the tensions within the cosmological parameters.

We use the following two likelihoods with the cross-spectra from Sect. 5.3.2 to estimate \(\tau\).

- Lollipop (Mangilli et al. 2015) is based on a modification of the Hamimeche and Lewis approach (Hamimeche & Lewis 2008) for cross-spectra at low multipoles. The
offset is proportional to an effective noise term \( \alpha_f = N_{\text{eff}} \approx \sqrt{2(2 + 1)} \Delta c_r \), derived from the HFPS set from which the covariance matrix is also computed. We use this likelihood only with PCL spectra in this paper (see also Planck Collaboration Int. XLVII 2016).

- SimBal is a likelihood code based on simulations, and targeted at estimating \( \tau \), as described in Appendix D. We apply it to both PCL and QML spectra. For QML spectra, we use either two independent subsets of HFPSs to determine the spectra and the covariance matrix, or (to limit the bias due to using the same small set of simulations) we use the full set, but with only a few eigenmodes to describe the systematic effects.

In the Lollipop likelihood, the bias is subtracted directly from the power spectra, while SimBal corrects for the bias by directly using the statistics of the simulations.

For QML, we define three versions of SimBal. SimBal1 and SimBal2 use covariance matrices determined from the simulation sets HFPS1 and HFPS2, respectively, while SimBal3 uses the covariance matrix determined from all 283 simulations (HFPS1, HFPS2, and HFPS3) and only four eigenmodes. These three versions of the SimBal likelihood deal in two different ways with the difficulty of the limited number of simulations (as discussed in Appendix D).

The two likelihoods sample \( \tau \) in the range 0.01–0.15 with a step \( \Delta \tau = 0.001 \), and with all other parameters, except \( \Delta \), fixed to the Planck 2015 best-fit values. We keep \( \Delta \) at the fixed value from Planck 2015 (since it is tightly constrained by the higher multipoles). It was shown in Sect. 2.5 that the main systematic effect left in the maps is small, being significant only for \( \ell \approx 2 \) and 3, and can be simulated and removed (see Sect. 6.2). Figure D.8 shows that taking \( \ell_{\text{min}} \) to be 2, 3, or 4 shifts the \( \tau \) posterior distributions by less than \( 4 \times 10^{-3} \), confirming that the final removal of this last systematic effect (by the subtraction of the simulated effect, combined with the use of QML cross-spectra) is very good. In Sect. 6.2, we test the robustness of our analysis with respect to the removal of residual systematics, and with respect to the two estimators of the power spectra described in Sect. 5.3. We also test the consistency of our results by using cross-spectra between HFI and LFI, specifically 70 \( \times \) 143. Cross-spectra to extract \( \tau \) (Fig. 37).

6.2. \( \tau \) determination from EE cross-spectra only

Figure 37 shows \( \tau \) posteriors computed by SimBal from the 100 and 143-GHz QML cross- and auto-spectra, both with and without debiasing. Debiasing makes essentially no difference for the 100 \( \times \) 143 cross-spectrum (blue full and dotted lines); however it makes a significant difference in the auto-spectra, as expected because the use of QML cross-spectra removes part of the systematics. In the following, we always use debiased EE 100 \( \times \) 143 cross-spectra to extract \( \tau \).

The accuracy of the SimBal likelihood in recovering \( \tau \) is tested using the HFPS set and shown in Fig. 38 for both QML and PCL spectra. The input value of \( \tau = 0.06 \) is recovered accurately as \( \tau = 0.059^{+0.005}_{-0.010} \) (QML, 83 realizations in HFPS1, with pixel-pixel covariance matrix from 100 realizations in HFPS2; see Appendix D) and \( \tau = 0.058^{+0.008}_{-0.015} \) (PCL, 83 realizations in HFPS1). This demonstrates that our method does not remove signal and provides an essentially unbiased estimator for \( \tau \). The QML estimator produces smaller error bars, as expected, with a narrower and more symmetrical distribution.

Figure 39 shows \( \tau \) posteriors for the data computed by Lollipop and SimBal from 100 \( \times \) 143 PCL and QML cross-spectra. For the PCL spectra, results from Lollipop and SimBal are fully consistent. The asymmetry of the posterior distribution at low \( \tau \) is smaller for SimBal than for Lollipop, due to SimBal’s better handling of the statistics of the \( C_l \)s (see Appendix D). For QML, the three SimBal estimates give consistent posterior distributions, with significantly narrower width than the PCL results. They therefore provide our tightest
constraints on \( \tau \). The near-coincidence of the high-\( \tau \) tails of the distributions would imply essentially identical upper limits on \( \tau \) for the PCL and QML approaches, if the posteriors were used to provide upper limits on the reionization redshift. However, the posteriors with QML cross-spectra show a clear detection of \( \tau \) at the level of 3.5\( \sigma \), as discussed quantitatively in Appendix D.

To test how efficiently cross-spectra between the two Planck instruments suppress uncorrelated systematics, we used the HFI HFPS1 and the LFI end-to-end simulations of low-multipole systematic effects (83 for HFI, 10 for LFI). In the LFI 70-GHz channel maps, residuals from calibration uncertainties dominate over systematic effects. They are at the same level as the dominant HFI systematic, but are lower than the noise (as shown in Sect. 4). To each of these simulations of systematic errors we add 100 CMB realizations, with an input value of \( \tau = 0.05 \). We then calculate 70 \times 100 and 70 \times 143 PCL cross-spectra and run the SimBaL likelihood.

Figure 40 (top) shows results from simulations. The peak values are not significantly biased with respect to the input value of \( \tau = 0.05 \). This indicates that the cross-correlation between LFI and HFI frequencies removes the simulated residual systematic effects rather well for both instruments. The distributions are asymmetric and not very smooth because of the small number of LFI realizations. They show full width at half maximum 1.5 to 2 times larger than that obtained for the QML estimate using the HFI frequencies alone. Figure 40 (bottom) shows results from data, specifically the HFI pre-2016 maps at 100 and 143 GHz, and the LFI 70-GHz 2015 released maps (Planck Collaboration VI 2016). As in the simulations, the \( \tau \) is extracted from the 70 \times 100 and 70 \times 143 PCL cross-spectra using SimBaL. The peak values and 68\% upper and lower limits are

\[
\tau = 0.049^{+0.015}_{-0.019} \text{ for the } 70 \times 100 \text{ cross-spectra,}
\]

\[
\tau = 0.053^{+0.012}_{-0.016} \text{ for the } 70 \times 143 \text{ cross-spectra.}
\]

Very low values are not excluded by these combinations of data, but the peak values are compatible with the baseline results from the HFI 100 \times 143 cross-spectrum discussed above.

Table 7 summarizes the results on the posterior distributions of \( \tau \) based on the HFI 100 \times 143 EE cross-spectra PCL and QML estimators shown in Fig. 39.

The QML results give a detection of \( \tau \) at more than 3.5\( \sigma \) (see Appendix D), with the smallest uncertainties obtained so far from CMB data. For the same likelihood method and sky fraction, a cosmic-variance-limited measurement would have an uncertainty of 0.006. The peak values obtained with the PCL and QML methods agree to within 0.006. Cross-spectra between the two Planck instruments (70 \times 100 and 70 \times 143) also give compatible results, but with larger uncertainties.

The most stringent results in Table 7 are obtained with the SimBaL likelihood from 100 \times 143 QML cross-spectra. Taking a conservative uncertainty between the three QML results, we obtain

\[
\tau = 0.055 \pm 0.009, \quad \text{lowE.} 
\]
We will refer to this as the “lowE” data set and likelihood\(^{10}\). There has been a significant decrease in the peak value of \(\tau\) since its first determination from CMB\(_T\)\(_E\) measurements in 2003 and subsequent refinement using \(EE\) measurements from 2006. Figure 41 shows the history of \(\tau\) estimates.

Reionization history models based on astrophysical observations of high redshift sources predict asymptotic values of \(\tau\) at high redshift in the range \(0.048 - 0.055\) (Fig. 7 of Mashian et al. 2016) or \(0.05 - 0.07\) (Fig. 2 of Robertson et al. 2015). Our results are fully consistent with these expectations. For the first time, the upper limit on \(\tau\) derived from CMB\(_E\) observations gives meaningful limits on how such models can be extrapolated to redshifts larger than 10.

7. Implications of a lower value of \(\tau\) for cosmological parameters

The first Planck results on polarization at low multipoles (Planck Collaboration XI 2016; Planck Collaboration XIII 2016), based on the LFI maps, gave a lower value of \(\tau\) than that given in the 9-year WMAP analysis (Hinshaw et al. 2013). We also showed that cleaning the WMAP polarization maps for polarized dust emission using the HFI 353-GHz maps led to a reduction in \(\tau\), consistent with the results from the LFI-based analysis. The results presented in this paper lead to even lower values of \(\tau\).

The amplitude of the reionization bump in the \(EE\) power spectrum at low multipoles scales approximately as \(\tau^2\). Low values of \(\tau\) are therefore difficult to measure from large-scale polarization measurements of the CMB. As this paper demonstrates, exquisite control of systematic errors, polarized foregrounds, and instrument noise are required in order to measure the small polarization signal induced by cosmic reionization. The main results presented in this paper are based on the 100 × 143 \(EE\) cross-spectrum, summarized in Fig. 39 and Table 7. The posteriors for \(\tau\) in Fig. 39 show clear narrow peaks, with maxima at \(\tau = 0.055\), indicating detection of an \(EE\) reionization feature. Furthermore, in Table 7 we find a 95% upper limit of \(\tau < 0.072\). This limit is consistent but significantly lower than the Planck+LowP LFI results, the Planck dust-cleaned WMAP results reported in Planck Collaboration XIII (2016), and the LFI×HFI results summarized in Fig. 40.

Current astrophysical observations exclude very low values of \(\tau\). If the Universe is abruptly reionized at redshift \(z_{\text{re}}\), the optical depth caused by Thomson scattering is (e.g., Shull & Venkatesan 2008)

\[
\tau = \frac{2\sigma_T (1 - Y_P) \Omega_b}{m_p} \frac{H_0}{8\pi G} \left[ \Omega_m(1 + z_{\text{re}})^3 + \Omega_\Lambda \right]^{1/2} - 1
\]

for the base ΛCDM model with a helium abundance by mass of \(Y_P\) (assuming that the helium remains neutral). The Gunn-Peterson test (Gunn & Peterson 1965; Fan et al. 2006) provides strong astrophysical evidence that the intergalactic medium was highly ionized by a redshift of \(z = 6.5\). For the Planck 2015 base ΛCDM parameters, Eq. (12) gives \(\tau = 0.039\) for \(z_{\text{re}} = 6.5\). This conservative astrophysical constraint on \(\tau\), which eliminates the low \(\tau\) regions of the posteriors shown in Fig. 39, is in excellent agreement with our current constraint. The result also stands in good agreement with the PlanckTT+lensing+BAO constraints reported in Planck Collaboration XIII (2016), \(\tau = 0.067 ± 0.016\), which makes no use of CMB polarization at low multipoles.

Of course the true value of \(\tau\) is important in understanding the formation of the first stars and the process of reionization,
but it also has an impact on cosmological parameters that are of more fundamental significance. This is illustrated in Fig. 42. The principal degeneracies are between and , and between and . However, is also correlated with the spectral index of the fluctuation spectrum, , which is set by early Universe physics. As we will see below, improving the constraint on helps break this particular degeneracy.

To assess the impact of our new polarization data on the cosmological parameters, we have constructed a simplified, low-multipole likelihood based on simulations that include systematic effects. This is in combination with the HFI-based likelihood discussed here. The values of and shift downwards.

Adding the Planck lensing measurements, which are compatible with lower values of , drives down again, close to the original lowP value:

\[
\tau = 0.066 \pm 0.016, \quad \text{PlanckTT+lowP+lensing.} \quad (15)
\]

These shifts, and in fact the low-multipole power deficit, are not of sufficiently high significance to suggest new physics. Moreover, the fact that adding Planck lensing causes to shift downwards suggests that is lower than the value in Eq. (13). Indeed alone gives the following constraint on :  

\[
\tau = 0.055 \pm 0.009, \quad \text{SimLow.} \quad (16)
\]

We can anticipate what will happen if we replace the lowP likelihood with a statistically more powerful polarization likelihood favouring a low value of – the main effect will be to shift towards lower values, with a proportionately smaller shift of , also to smaller values. Furthermore this would not be consistent with solving the high-multipole peak smoothing through an underestimate of the effect of lensing. In fact, adding the Planck lensing measurement to SimLow and PlanckTT has a small impact on the value of , giving .

Figure 42 compares the SimLow and lowP parameter constraints on , , and , while Table 8 gives numerical results for parameters of the base CDM model. The tighter constraint on brought by SimLow reduces the correlation between and , and leads to slightly tighter bounds on . However, larger parameter changes are seen for and , each changing by about 1σ. We specifically find

\[
\tau = 0.058 \pm 0.009, \quad \text{PlanckTT+SimLow,} \quad (17)
\]

in excellent agreement with the result from SimLow alone. The present day amplitude of the fluctuations, , decreases by about 1σ and its uncertainty shrinks by about 33%. This shift goes in the right direction to reduce the tensions with cluster abundance and weak galaxy lensing, as discussed in Planck Collaboration XIII (2016), although it is not yet sufficient to remove them entirely.

Changes in most of the other cosmological parameters are small, with deviations being less than 0.5σ. The largest deviation is in the spectral index , due to its partial correlation with . This slight decrease in means that we can now reject the scale-invariant spectrum at the 6.7σ level (8.7σ when using the high- polarization data). The Hubble constant decreases by 0.4σ; within the framework of the base CDM model, this increases the tension with some recent direct local determinations of (Riess et al. 2016) to around 3.2σ.

The use of SimLow in place of lowP has little effect on most of the usual extensisons to the CDM model, as can be seen in Table 9. The number of relativistic species, for example, remains compatible with 3. The phenomenological parameter is essentially unchanged, and still discrepant at roughly the 2σ level from its expected value of 1. Additionally, the running of the spectral index is constrained to be even closer to zero.

Due to the lowering of the normalization, the CMB constraint on neutrino masses improves from to (PlanckTT+lowP) to (PlanckTT+SimLow) and (PlanckTTTTTEEE+SimLow). When adding BAO information (see Planck Collaboration XIII 2016, for details), these constraints improve further to and .

Adding the Planck TT + lowTEB Planck TT + SimLow

Fig. 42. Parameter constraints for the base CDM cosmology, illustrating the degeneracy and the impact of replacing the LFI-based lowP likelihood used in the 2015 Planck papers with the HFI-based SimLow likelihood discussed here. The values of and shift downwards.
Planck Collaboration: Large-scale polarization and reionization

Table 8. Parameter constraints for the base ΛCDM cosmology (as defined in Planck Collaboration XVI 2014), illustrating the impact of replacing the LFI-based lowP likelihood (used in the 2015 Planck papers) with the HFI-based SimLow likelihood discussed in the text.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>PlanckTT+lowP 68% limits</th>
<th>PlanckTT+SIMlow 68% limits</th>
<th>PlanckTTTEEE+lowP 68% limits</th>
<th>PlanckTTTEEE+SIMlow 68% limits</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ω_h^2</td>
<td>0.02222 ± 0.00023</td>
<td>0.02214 ± 0.00022</td>
<td>0.02225 ± 0.00016</td>
<td>0.02218 ± 0.00015</td>
</tr>
<tr>
<td>Ω_k</td>
<td>0.1197 ± 0.0022</td>
<td>0.1207 ± 0.0021</td>
<td>0.1198 ± 0.0015</td>
<td>0.1205 ± 0.0014</td>
</tr>
<tr>
<td>100Ω_M</td>
<td>1.04085 ± 0.00047</td>
<td>1.04075 ± 0.00047</td>
<td>1.04077 ± 0.00032</td>
<td>1.04069 ± 0.00031</td>
</tr>
<tr>
<td>τ</td>
<td>0.078 ± 0.019</td>
<td>0.0581 ± 0.0094</td>
<td>0.079 ± 0.017</td>
<td>0.0596 ± 0.0089</td>
</tr>
<tr>
<td>ln(10^10A_s)</td>
<td>3.089 ± 0.036</td>
<td>3.053 ± 0.019</td>
<td>3.094 ± 0.034</td>
<td>3.056 ± 0.018</td>
</tr>
<tr>
<td>n_s</td>
<td>0.9655 ± 0.0062</td>
<td>0.9624 ± 0.0057</td>
<td>0.9645 ± 0.0049</td>
<td>0.9619 ± 0.0045</td>
</tr>
<tr>
<td>H_0</td>
<td>67.31 ± 0.96</td>
<td>66.83 ± 0.91</td>
<td>67.27 ± 0.66</td>
<td>66.93 ± 0.62</td>
</tr>
<tr>
<td>Ω_m</td>
<td>0.315 ± 0.013</td>
<td>0.321 ± 0.013</td>
<td>0.3156 ± 0.0091</td>
<td>0.3202 ± 0.0087</td>
</tr>
<tr>
<td>σ_8</td>
<td>0.829 ± 0.014</td>
<td>0.8167 ± 0.0095</td>
<td>0.831 ± 0.013</td>
<td>0.8174 ± 0.0081</td>
</tr>
<tr>
<td>σ_8Ω_m</td>
<td>0.466 ± 0.013</td>
<td>0.463 ± 0.013</td>
<td>0.4668 ± 0.0098</td>
<td>0.4625 ± 0.0091</td>
</tr>
<tr>
<td>σ_8Ω_m^0.25</td>
<td>0.621 ± 0.013</td>
<td>0.615 ± 0.012</td>
<td>0.623 ± 0.011</td>
<td>0.6148 ± 0.0086</td>
</tr>
<tr>
<td>z_eq</td>
<td>9.8918 ± 0.16</td>
<td>8.11 ± 0.93</td>
<td>10.017 ± 0.15</td>
<td>8.24 ± 0.88</td>
</tr>
<tr>
<td>10^9A_s e^{-2τ}</td>
<td>1.880 ± 0.014</td>
<td>1.885 ± 0.014</td>
<td>1.882 ± 0.012</td>
<td>1.886 ± 0.012</td>
</tr>
<tr>
<td>Age/Gyr</td>
<td>13.813 ± 0.038</td>
<td>13.829 ± 0.036</td>
<td>13.813 ± 0.026</td>
<td>13.826 ± 0.025</td>
</tr>
</tbody>
</table>

Notes. We also present here the change when including the high-ℓ polarization.

Table 9. Constraints on 1-parameter extensions of the base ΛCDM model obtained using the PlanckTT likelihood in combination with lowP and SimLow.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>PlanckTT+lowP 95% limits</th>
<th>PlanckTT+SIMlow 95% limits</th>
<th>PlanckTTTEEE+lowP 95% limits</th>
<th>PlanckTTTEEE+SIMlow 95% limits</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ω_k</td>
<td>−0.052 ± 0.049</td>
<td>−0.053 ± 0.044</td>
<td>−0.040 ± 0.038</td>
<td>−0.039 ± 0.032</td>
</tr>
<tr>
<td>Σ_m [eV]</td>
<td>&lt;0.715</td>
<td>&lt;0.585</td>
<td>&lt;0.492</td>
<td>&lt;0.340</td>
</tr>
<tr>
<td>N_{eff}</td>
<td>3.13±0.64 ± 0.63</td>
<td>2.97±0.58 ± 0.53</td>
<td>2.99±0.41 ± 0.39</td>
<td>2.91±0.39 ± 0.37</td>
</tr>
<tr>
<td>Y_p</td>
<td>0.252±0.041 ± 0.042</td>
<td>0.242±0.039 ± 0.040</td>
<td>0.250±0.026 ± 0.027</td>
<td>0.242±0.026 ± 0.026</td>
</tr>
<tr>
<td>d_n_s/dln k</td>
<td>−0.008±0.016 ± 0.016</td>
<td>−0.004±0.015 ± 0.015</td>
<td>−0.006±0.014 ± 0.014</td>
<td>−0.003±0.014 ± 0.013</td>
</tr>
<tr>
<td>r_0.002</td>
<td>&lt;0.103</td>
<td>&lt;0.111</td>
<td>&lt;0.0987</td>
<td>&lt;0.111</td>
</tr>
<tr>
<td>w</td>
<td>−1.54±0.62 ± 0.50</td>
<td>−1.57±0.61 ± 0.49</td>
<td>−1.55±0.58 ± 0.48</td>
<td>−1.59±0.58 ± 0.46</td>
</tr>
<tr>
<td>A_L</td>
<td>1.12±0.21 ± 0.20</td>
<td>1.12±0.20 ± 0.18</td>
<td>1.15±0.16 ± 0.15</td>
<td>1.15±0.13 ± 0.12</td>
</tr>
</tbody>
</table>

Notes. We note that contrary to Table 8, where all the parameters correspond to a single cosmological fit, the results in each line here are obtained from a separate ΛCDM+extension fit. Uncertainties are at 95% CL.

The HFI polarization measurements presented in this paper reduce some of the tensions for some of the cosmological parameters, but have no substantial impact on the qualitative conclusions of the Planck 2015 cosmology papers. In particular, the ΛCDM model remains an excellent description of the current data.

Further interpretation of these results in terms of reionization models can be found in the companion paper Planck Collaboration Int. XLVII (2016). A more complete quantitative description of all the cosmological consequences of the new HFI-based constraints, along with a complete reanalysis of the high-ℓ polarization using these new data, will be performed in a forthcoming Planck release.

8. Conclusions

This paper presents a value of the parameter τ derived solely from low-multipole EE polarization, which is both the most accurate to date and the lowest central value. It depends on the high-ℓ multipoles of the TT power spectrum only through the constraint required to fix A_s e^{-2τ}.
Measurements of polarized CMB anisotropies on these large (>10^4) scales require all-sky coverage and very low noise. Only space experiments with great stability, multiple redundancies, and enough frequencies to remove Galactic foregrounds, can achieve all of these simultaneously. The WMAP satellite was the first to reach most of these goals, with two telescopes to directly measure very large scales, passively cooled detectors, and nine years of observations; however, its lack of high frequencies did not allow a sufficiently accurate dust foreground subtraction to be carried out. The Planck mission achieved much lower noise, especially with the 100 mK bolometers of the HFI. Scanning the sky in nearly great circles at 1 rpm for 2.5 yr, Planck HFI required extreme stability and many levels of redundancy to measure the polarized CMB on the largest scales. The challenge was such that, for the first two cosmological data and science releases by the Planck team, there were still obvious signs of poorly understood systematic effects, which prevented the use of large-scale HFI polarized data.

At 545 and 857 GHz, calibration is not as accurate as in the CMB-calibrated channels (70–353 GHz), but polarized dust emission can be removed well enough that τ is unaffected by dust residuals. Furthermore, most of the synchrotron foreground that is uncorrelated with dust is also mostly removed when using only 100 × 143 cross-spectra. At CMB frequencies, polarized systematic effects have now been understood and modelled. One systematic effect is not yet corrected in the maps, but is removed as a small correction to the power spectra using simulations. Finally, the use of the 100 × 143 QML cross-spectrum reduces even further the impact of the remaining systematic effects at CMB frequencies. These advances enable a measurement of τ to be made using only the low E multipole from HFI, along with the high-multipole T T constraint on A_s e^{2νT}. The path is now clear to the final Planck release in 2016, which will provide full-sky polarized CMB maps that are reliable on all scales.

This τ determination fully reconciles the CMB results with other astrophysical measurements of reionization from sources at high redshift. It also gives constraints on the level of reionization at redshifts beyond that of the most distant sources (z > 10).

Large-scale CMB polarization measurements ultimately contain more information on the reionization period than just the value of τ, and can also constrain turbulence in interstellar magnetic fields and B-mode polarization due to primordial gravitational waves, hence the physics of inflation and the early Universe. This last objective requires not only the knowledge of τ that is now achievable, but also data that are fully noise-limited at all frequencies.

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Appendix A: HFI systematic errors

Here we describe tests of known systematic errors in the HFI instrument and their effects on low-multipole polarization.

A.1. Glitches

Glitches induced by cosmic ray hits on the bolometers are a major source of systematic errors in HFI, and are described in detail in (Planck Collaboration VI 2014; Planck Collaboration X 2014; Planck Collaboration VII 2016). In the TOI processing software, glitches are detected via their transient nature, and are then masked and corrected.

Additionally, a long-tail glitch template, built from stacking many events, is fitted to each detected event, and the tail is subtracted from the data. This procedure reduces the noise power by an order of magnitude at frequencies around 0.05 Hz. Uncertainties in this correction contribute to, but do not dominate, the low frequency noise of the detectors. The size of this contribution has been evaluated at the TOI level using simulations in Planck Collaboration VI (2014) and Planck Collaboration X (2014), where we have shown that it accounts for from a few percent up to 30% of the noise, depending on the detector, at frequencies between 0.016 and 0.1 Hz, and is negligible at higher frequencies.

Glitches remaining below the detection threshold contribute to the white noise at a level of 3 to 6%. Polarization-sensitive bolometers (PSBs) in the same module see many coincident events, so both detected and undetected glitches are a potential contaminant of the polarization measurements.

To check the effect of glitches on the polarization maps and power spectra, we used the end-to-end simulations, which incorporate a physically motivated model of the glitches (Planck Collaboration X 2014; Catalano et al. 2014). We simulated the full mission data for four detectors at 143 GHz (the first detector), at frequencies between 0.016 and 0.1 Hz, and is negligible at higher frequencies.

Glitches remaining below the detection threshold contribute to the white noise at a level of 3 to 6%. Polarization-sensitive bolometers (PSBs) in the same module see many coincident events, so both detected and undetected glitches are a potential contaminant of the polarization measurements.

To check the effect of glitches on the polarization maps and power spectra, we used the end-to-end simulations, which incorporate a physically motivated model of the glitches (Planck Collaboration X 2014; Catalano et al. 2014). We simulated the full mission data for four detectors at 143 GHz (the first detector), with and without glitches. The level of glitch residuals was evaluated by computing the power spectra of the map differences from the two sets, after running the processing pipeline (including the glitch removal) in simulations with glitches only, and using the same flags in both cases. The results, shown in Fig. A.1, indicate that, after correction, contamination of the polarization maps and power spectra when masking all events detected by 15 or more coincident glitches in the focal plane (120,000 events).

A.3. Baseline removal and non-linearities

A low frequency baseline built from the dark bolometer TOI is subtracted from all other bolometers, removing the common effect of the temperature fluctuation of the bolometer plate. This has no significant residual effect on large angular scales, as shown using an end-to-end simulation (see Fig. 20 of Planck Collaboration VII 2016). The effect at low multipoles is a small fraction of the signal (<0.3% for \(\ell < 20\) and 2.5% at \(\ell = 4\)). This leads to levels an order of magnitude smaller than the EE fiducial model at all multipoles.

The bolometers have a small non-linear response associated with the relatively large changes in the operating point associated with the slow drift of the temperature of the bolometer plate (with the instantaneous linear gain being given by the slope of the tangent at the operating point); these changes in the temperature of the bolometer plate come from Galactic cosmic rays.
ray rate modulation by the inhomogeneities of the solar wind, on timescales of hours to weeks (2 to 10 $\mu$K), as well as the long-term solar cycle modulation (80 $\mu$K) during the mission. The relative gain variation for a 100 $\mu$K temperature change is $2\sim3 \times 10^{-3}$, and is taken into account as a first estimate of the non-linear response term on the signal. The second-order term is two orders of magnitude smaller for a 100 $\mu$K temperature change (a few $10^{-5}$), a correction that is below other effects considered here. Planck HFI Core Team (2011a) predicts a $10^{-5}$ gain change due to the optical loading variations coming from the CMB solar dipole at 143 GHz, the largest CMB signal.

A second small non-linearity is due to the changes in the temperature of the warm electronics boxes on the satellite. The coefficients of this gain change have been measured in ground tests, and the effect has been propagated to the power spectrum using the end-to-end simulations and the measured temperature history of the mission. The results are shown in Fig. A.2. The correction is less than $10^{-4} $ $\mu$K$^2$ in $C_\ell$ for all multipoles. The uncertainty on this correction is thus negligible.

A third non-linearity, due to the ADC, will affect the thermal baseline differently for different detectors. This will induce a residual effect at low frequencies which contributes to the uncorrelated $1/f$ noise.

### A.4. He-JT cooler pickup

Electrical coupling between the He-JT cooler drive and the bolometer readout (which are phase-locked) appears as very narrow lines (called “4-K lines”) in the power spectrum of the TOI at harmonics of 10 Hz. These are removed from the TOI (see, e.g., Planck Collaboration VII 2016). Residuals from this removal process can affect the angular power spectra of the CMB, although due to the near-constant spin rate of the Planck spacecraft, the 4-K lines project to the sky at discrete angular scales.

Fig. A.2. Simulated contribution of warm readout electronics drifts on the auto-power spectra of 143-detset1. The red curves show the contribution of the electronics drift compared to the total map power (orange) and the $F-EE$ input to the simulations (black). The green curve is an estimate of the noise level based on the half-ring differences.

<table>
<thead>
<tr>
<th>Detector</th>
<th>Input crosstalk [%]</th>
<th>Resolved calibration change [%]</th>
</tr>
</thead>
<tbody>
<tr>
<td>217-5a</td>
<td>0.224</td>
<td>0.227</td>
</tr>
<tr>
<td>217-5b</td>
<td>0.159</td>
<td>0.161</td>
</tr>
<tr>
<td>217-6a</td>
<td>0.112</td>
<td>0.116</td>
</tr>
<tr>
<td>217-6b</td>
<td>0.112</td>
<td>0.115</td>
</tr>
<tr>
<td>217-7a</td>
<td>0.447</td>
<td>0.450</td>
</tr>
<tr>
<td>217-7b</td>
<td>0.398</td>
<td>0.403</td>
</tr>
<tr>
<td>217-8a</td>
<td>0.200</td>
<td>0.204</td>
</tr>
<tr>
<td>217-8b</td>
<td>0.126</td>
<td>0.129</td>
</tr>
</tbody>
</table>

Notes. The calibration change solved by SRo11 is compared to the simulated input crosstalk for different detectors.

The lowest frequency line, seen at 10 Hz in the TOI, projects to $\ell \approx 600$. Since this feature is well away from the reionization structure in the angular power spectrum that we consider here, we do not attempt further cleaning of these features from the data.

### A.5. Detector crosstalk

Electrical coupling, or crosstalk, between the pair of detectors in a PSB can create errors in the recovered polarization. The ground-based calibration of HFI and the in-flight measurements of current crosstalk put an upper limit to this coupling at the level of $10^{-3}$ (Pajot et al. 2010). Planck HFI Core Team (2011a) states this limit as $\sim60$ dB. Nevertheless, the square modulation of the bias current of the bolometers was kept at a constant amplitude throughout the mission.

The voltage crosstalk is more relevant than the current crosstalk for the coupling of the signal between detectors, and is estimated in-flight using cosmic ray glitches. While the vast majority of the long glitches are coincident between the a and b detectors within a PSB pair, there is also a population of coincident short glitch detections, which have a shift in time on the order of tens of milliseconds that cannot be due to a single particle, and must come from crosstalk. These phase-shifted coincidences are stacked to solve for a crosstalk amplitude, which is typically in the range $1\sim3 \times 10^{-3}$ for pairs of PSB detectors. The crosstalk level is consistent from a to b bolometers and from b to a, in all cases.

Using the end-to-end simulations, we propagate the measured voltage crosstalk between the PSBs into maps of the polarized sky using the glitch-measured crosstalk amplitudes and phase shifts, and compare these to a simulated no-crosstalk case. The main effect of the crosstalk is to bias the relative calibration between detectors. The SRo11 map-making algorithm recovers the calibration correction due to crosstalk to very good precision (as shown in Table A.1).

Figure A.3 shows the $EE$ and $BB$ angular power spectra of the simulations. Introducing detector crosstalk in the simulation changes the recovered polarization signal by a small amount; the absolute value of the difference is lower than the noise variance in the simulation. This might need to be corrected in future for the detection of very low level polarized signals.
where we have assumed that \( C \) and \( E \) were shown to induce an uncertainty below 10% of the systematic uncertainties in the ground apparatus. Such error lev-

The simulations, with and without simulated crosstalk, respectively. The (dashed black). The orange and blue crosses show the total power in
culation, to which a realization drawn from the noise variance is added
crosstalk. Red crosses indicate the F-
Fig. A.3. 

For each detector, estimated to be lower than 0.

In order to confirm the ground calibration measurements on
the sky data, we use the \( T B \) and \( EB \) spectra to check for a possible
global rotation of the focal plane at 100, 143, and 217 GHz,
independently. Rotation by an angle \( \alpha \) induces \( E \) and \( B \) mixing,
leading to spurious \( T B \) and \( EB \) signals given by

\[
C_{T B}^{\ell,\text{rot}} = C_{T}^{\ell} \sin(2\alpha), \quad (A.1)
\]

\[
C_{E B}^{\ell,\text{rot}} = \frac{1}{2} \left( C_{E}^{\ell} - C_{B}^{\ell} \right) \sin(4\alpha), \quad (A.2)
\]

where we have assumed that \( C_{T}^{\ell} \) and \( C_{E}^{\ell} \) equal zero for the

Combining Eqs. (A.1)–(A.4), we can build the five parameter
(\( \alpha, \beta_{1}, \beta_{2}, \epsilon_{1}, \epsilon_{2} \)) model to be fitted to the \( T B \) and \( EB \) spectra at 100, 143, and 217 GHz.

To compute the angular power spectra, we subtract dust emission from the \( Q \) and \( U \) detset maps, using the 353 GHz maps as dust templates. Masking 50% of the sky as well as point sources, we use Xpo1 (Tristram et al. 2005) to compute the cross-spectra between the two detsets in each channel, which efficiently suppresses the noise bias. We sample the model parameter space using a Markov chain Monte Carlo (MCMC) algorithm from which the probability densities of the parameters may be recovered. The angle \( \alpha \) is constrained by the MCMC to the following values (68% CL, statistical only), depending on the frequency and spectrum examined.

- 100 GHz: \( \alpha^{T B} = 0.01 \pm 0.21; \alpha^{EB} = 0.46 \pm 0.17 \);
- 143 GHz: \( \alpha^{T B} = 0.11 \pm 0.16; \alpha^{EB} = 0.29 \pm 0.13 \);
- 217 GHz: \( \alpha^{T B} = 0.56 \pm 0.27; \alpha^{EB} = 0.23 \pm 0.28 \).

The beam mismatch parameters are not constrained by the MCMC, but they have little impact (i.e., \( \lesssim 1\sigma \)) on the values of \( \alpha \) quoted above. Whatever the channel and spectra, the angle is never significantly different from zero, and always smaller than the average errors on PSB orientation (~1°) measured on the ground prior to launch (Rosset et al. 2010).

Comparison with the polarization orientation of the Crab nebula was discussed in Sect. 3.5.2 of (Planck Collaboration XXVI 2016) and shown to be consistent with the above numbers.

We conclude that the uncertainties of the instrumental polarization parameters as set up in the data processing pipeline have no significant effects on the low-\( \ell \) \( EE \) and \( BB \) cross-spectra, and are also in broad agreement with preflight determinations.

**Appendix B: The SRoll global solution**

This Appendix describes the SRoll method for constructing polari-
zied sky maps from the HFI data. The method is divided into three steps, shown schematically in Fig. B.1. The first step bins the time-ordered information into HEALPix pixels per period of stable satellite pointing to reduce the amount of data (Sect. B.1.3). The second step fits systematic effects, 1/f noise, and calibration using differences between measurements in the same HEALPix pixel (Sects. B.1.6 and B.1.7). The third step cleans the data using the fitted parameters, and projects the signal to make polarized maps (Sect. B.1.8). The quality of the final maps depends on the efficiency with which the non-sky signals
can be characterized during the fitting procedure in the second step. After describing the method, this appendix discusses masks in Sect. B.2, presents simulations in Sect. B.3, and tests and characterizes the efficiency with which SR011 can clean the signal in Sect. B.4.

B.1. Method

B.1.1. Systematic effects considered

The method corrects for baseline drifts due to 1/f noise in a similar way as the standard unpolarized destriping method used for previous Planck products (Planck HFI Core Team 2011b; Planck Collaboration VIII 2014, 2016), but improves on that method by solving for the amplitudes of templates of additional systematic effects that are not fully corrected in the standard TOI processing, as well as leakage from temperature to polarization. The systematic effects considered are:

1. gain variation due to residual analogue-to-digital converter non-linearity (ADC non-linearity);
2. pick-up of Galactic emission and the orbital and solar dipoles in the far sidelobes of the telescope (i.e., the response at angles greater than 5° from the main beam axis);
3. temperature-to-polarization leakage due to bandpass mismatch between bolometers, from foreground emission with SEDs differing from that of the CMB, namely dust, free-free, and CO;
4. temperature-to-polarization leakage due to calibration mismatch on the CMB dipole;
5. large-scale residual transfer functions that are not corrected in the deconvolution step of the standard TOI processing.

Figure B.1 gives an overview of the main modules of SR011.

B.1.2. Data model

All PSB bolometers in a given frequency band are used to solve for the sky map at a given frequency. The data for each bolometer (indexed with \( b \)) are divided into pointing periods (indexed with \( i \)) and into periods of constant gain (indexed with \( k \)). The definitions of these data periods are described in detail in Sect. B.1.5. The data sample indexed with \( p \) in the equation below corresponds to a pixel within an HPR (HEALPix ring), not a sample in a time series.

We model the HPR data as

\[
g_{b,k} M_{b,i,p} = I_p + \rho_b \left[ Q_p \cos(2\phi_{b,i,p}) + U_p \sin(2\phi_{b,i,p}) \right] \\
+ \sum_{h=1}^{n_{map}} \gamma_{b,h} V_{b,i,p,h} + \sum_{l=1}^{n_{map}} L_{b,l} C_{b,i,p,l} \\
+ D_{b,i,p}^{n} + D_{b,i,p}^{d} + F_{b,i,p}^{s} + O_{b,i} + g_{b,k} N_{b,i,p}.
\]  

(B.1)

where:

- \( g_{b,k} \) is the absolute gain of bolometer \( b \) during gain period \( k \).
- \( M_{b,i,p} \) is the bolometer signal sample data in pixel \( p \) of pointing period \( i \).
- \( I_p \), \( Q_p \), and \( U_p \) represent the common sky maps, excluding the dipole, seen by all bolometers in pixel \( p \).
- \( \rho_b \) is the polar efficiency, fixed at the ground measurement value.
- \( \phi_{b,i,p} \) is the detector angle of polarization compared to the north-south axis.
- \( V_{b,i,p,h} \), \( L_{b,l} \), and \( C_{b,i,p,l} \) are the templates of foreground components \( h \). The dust component is fitted at all frequencies, the CO component is fitted at all frequencies except 143 GHz, and the free-free component is fitted at 100 GHz only. The templates for the components, without bandpass mismatch leakage, are taken initially from the Planck 2013 results, and then iterated with the maps from previous iterations. The polarization of the foreground is taken into consideration only for the dust.
- \( O_{b,i} \) is the 1/f noise effect modelled as one offset per pointing period. We set \( \sum_{p=1}^{N_{pix}} O_{b,i} = 0 \) since the Planck data provide no information on the monopole.
- \( N_{b,i,p} \) is white noise.

B.1.3. HPR computation

The SR011 method is based on HP2s as for the Planck 2015 data release (see Sect. 6.1 of Planck Collaboration VIII 2016). This procedure reduces the amount of data, and in the limit that the spin-axis pointing, noise, and systematic effects are constant during a pointing period, the information loss is negligible.

Each detector’s TOI for each period of stable spin-axis pointing is binned into HEALPix pixels at \( N_{side} = 2048 \), compressing the data. Furthermore, all sky-map templates fitted by SR011 are converted from TOI to HPR (dipoles, CO maps, dust map, and free-free map). The residual transfer function templates (see Sect. B.4.3) are computed at the timeline level and then projected into HP2s.

B.1.4. Empirical transfer functions

Differential time response on long timescales remaining in the data from the PSBs can create spurious large-scale polarization residuals. Estimates of the time response of the bolometers and electronics, referred to as “very long time constants” (VLTCs), determined using planet crossings and stacked cosmic ray glitches, have been deconvolved from the TOI (Planck Collaboration VII 2014, 2016). This technique is not sensitive to time response on timescales longer than one second.

Residuals of far sidelobe (FSL) contributions after removal in the ring-making phase, together with VLTCs, induce small
B.1.5. Gain step optimization

SRo11 assumes that the gain of each bolometer is constant over multiple rings. $N_{\text{gain}}$ time-steps are chosen in such a way that the total dipole gain variance is constant over each period $k$. If there is significant variation of the effective gain within a defined period, then of course the method cannot account for it. This is a problem only for the very long gain periods required when the dipole or Galactic signal happens to be weak. These periods are, by definition, characterized by the relatively small dynamical range of the signal, and therefore a correspondingly small leakage from temperature to polarization. Furthermore, in these periods the signal samples only a small range in the ADC, so it is unlikely to exhibit much in the way of gain variations from the ADC non-linearity.

Figure B.2 shows the effects of the sampling on the variable gains solved by SRo11: gain periods of uniform length increase the instability of the gain determination, while optimized sampling improves stability.

B.1.6. Variable gain measurement

Solving for gain variability necessarily involves solving a non-linear least squares equation. SRo11 uses an iterative scheme to solve for the gains $g_i$ of the bolometer at each ring $i$. At
iteration \( n \) we have

\[ g_{i,n+1} = g_{i,n} + \Delta g_{i,n}, \quad (B.2) \]

the goal being to fit \( \Delta g_{i,n} \). We can also remove the FSL effect as

\[ g_{i,n} M_{i,p} = g_{i,n} M_{i,p} - F_{\text{dip}}^{\text{eq}} - F_{\text{gal}}^{\text{eq}}. \quad (B.3) \]

Using Eqs. (B.2) and (B.3), Eq. (B.1) becomes

\[ g_{i,n} M_{i,p} = (1 - \Delta g_{i,n}) \left[ I_p + \rho \left( Q_p \cos(2\phi_{i,p}) + U_p \sin(2\phi_{i,p}) \right) \right] + D_{\text{tot}}^{\text{eq}} + \sum_{h=1}^{\text{max}} \gamma_h V_{h,i,p} + \sum_{l=1}^{\text{max}} L_{b,l} C_{i,p} + g_{i,n} N_{i,p}, \quad (B.4) \]

where:

- \( i \) and \( p \) are the indices of the ring \( i \) and the HEALPix pixel \( p \) (recall that the gain is assumed to be constant over multiple rings, as described in Sect. B.1.5, and the gain for ring \( i \) means the gain for the gain period \( k \) that contains the ring \( i \));
- \( g_i \) is the gain of the bolometer in ring \( i \);
- \( M_{i,p} \) is the measured bolometer signal for the HEALPix pixel \( p \) of ring \( i \);
- \( I_p, Q_p, U_p \) is the common sky map, excluding the dipole, seen by all bolometers in HEALPix pixel \( p \);
- \( D_{\text{tot}}^{\text{eq}} = D_{\text{sol}}^{\text{eq}} + D_{\text{orb}}^{\text{eq}} \), where \( D_{\text{sol}}^{\text{eq}} \) is the solar dipole for the HEALPix pixel \( p \) and \( D_{\text{orb}}^{\text{eq}} \) is the orbital dipole at ring \( i \) for the HEALPix pixel \( p \).

Based on the destriping method of Keihänen et al. (2004), for a known gain \( g_{i,n} \), Eq. (B.4) solves for \( \Delta g_{i,n}, \gamma_h, b, \) and \( L_{b,l} \). Should \( D_{\text{sol}}^{\text{eq}} \) not be degenerate with the foregrounds or the systematic effects, \( \Delta g_{i,n} \) would be the exact difference between the gain of the first iteration and the real gain, and the method would converge in a single step. Unfortunately, foregrounds projected on a ring have a dipole component that leads to a degeneracy between the first iteration and the real gain, and the method would converge in a single step. Unfortunately, foregrounds projected on a ring have a dipole component that leads to a degeneracy between the

\[ I_p = I_p + g_i \eta D_{\text{tot}}^{\text{eq}}, \quad (B.5) \]

where \( I_p \) is orthogonal to \( D_{\text{tot}}^{\text{eq}} \) during the period of roughly constant gain (i.e., the period \( k \) as defined in Sect. B.1.5).

Figure B.3 shows the histogram of this \( \eta \) parameter. Its dispersion is explained by the variation during the mission of the orientation of the ring with respect to the Galactic plane. Moreover, the amplitude of the dipolar component of the Galaxy increases with frequency. Thus the magnitude of the degeneracy increases, and then the dispersion of the \( \eta \) parameter increases with frequency as well. Then, Eq. (B.2) becomes

\[ g_{i,n+1} = g_i + \eta \Delta g_{i,n}. \quad (B.6) \]

At all frequencies \( |\eta| < 1 \), and \( g_{i,n} \to g_i \) when \( n \to \infty \). Thus the degeneracy between \( I_p \) and \( D_{\text{tot}}^{\text{eq}} \) impacts only the convergence rate of the algorithm; SRO11 always converges to the correct gain estimate when the data model is an accurate description of the sky signal.

Table B.1 shows how the gain convergence works in a simulation without noise for various \( \eta \) values. When \( \eta = 0 \), the gain is solved in one iteration. When \( \eta \) is non-zero, the gain convergence reaches \( 10^{-3} \) after only four iterations. Thus, SRO11 uses four iterations.

These simulations also test the degeneracy with bandpass leakage. They show that the degeneracy between gain determination and bandpass leakage is small. As we will see below, more detailed simulations that contain noise enable us to control more precisely the level of accuracy that SRO11 reaches when fitting gain and other systematics.

We find that the \( \eta \) variance increases when smaller gain-stable periods are used. Figure B.3 shows that the gain-stable period cannot be decreased at 353 GHz, otherwise this would lead to \( |\eta| > 1 \). That is why we define longer periods at 353 GHz than at other frequencies. Masking pixels where the Galactic signal is degenerate with the dipole signal also helps to obtain \( |\eta| < 1 \).

An alternative solution could use a Galactic model to fit gain variations on shorter timescales. This procedure would work if...
the following requirements were met: first, the Galactic template must not have noise that correlates with the data, such as using a previous map version at the same frequency; second, the Galactic template has to have no residual dipole remaining from a previous calibration mismatch; and thus, SRoll currently solves for gain variations with dipole residual fitting.

B.1.7. Final minimization

During the last step of the SRoll algorithm, the minimization is the same as in the previous iteration, but the dipole is not removed. The minimization then adjusts the other parameters (offsets, VLTC, and bandpasses) with the gains as they were determined at the previous step.

B.1.8. Projection onto maps

SRoll projects time-ordered information to pixel maps using gains and systematic effects fitted during the previous steps. From Eq. (B.1) we obtain

$$g_i M_{i,p} - R_{i,p} = I_p + \rho_p \left[ \cos(2 \phi_{i,p}) Q_p + \sin(2 \phi_{i,p}) U_p \right].$$

Thus, inside each pixel we can define

$$\chi_p^2 = \sum_{i} \frac{I_p + \rho_p \left[ \cos(2 \phi_{i,p}) Q_p + \sin(2 \phi_{i,p}) U_p \right] - g_i M_{i,p} + R_{i,p}}{\sigma_i^2}.$$  (B.8)

A linear system is used to find the values of $I_p$, $Q_p$, and $U_p$ that minimize this $\chi^2$.

### B.2. Masks

The solution for the map parameters is done with the sky partly masked. This masking has two goals, firstly, to avoid regions of the sky with time-variable emission, and secondly to avoid regions with a strong signal gradient. Thus, the brightest point sources are removed (e.g., the flux of 3C 273 is strong and it changes during the mission). The Galactic plane is also masked, due to the strong signal gradients there. Nevertheless, a relatively large sky coverage is needed to properly solve for the bandpass mismatch extracted from the Galactic signal. Figure B.4 shows the masks used and gives the sky fractions used in the map solution.

### B.3. End-to-end simulations

#### B.3.1. General description

Simulations are used to characterize the performance of SRoll. We start from simulated TOI data sets after TOI processing, including the total CMB dipole (solar and orbital), CMB anisotropies, Galactic and extragalactic foregrounds, and noise. These are processed to simulate all systematics relevant for map-making. The SRoll mapmaking is then applied to these TOIs to obtain the so-called E2E simulated frequency band $I$, $Q$, and $U$ maps and associated $TT$, $EE$, and $BB$ power spectra. For testing purposes, one can choose specific subsets of input signals, systematic effects, and processing modules.

Building a simulation data set with 100 noise and 100 CMB realizations was not feasible for this paper. We thus test if the CMB can be simulated separately from the noise and systematics and for this purpose two sets of TOIs are simulated, the first including all the inputs, and the second including all inputs except for CMB anisotropies. Maps are made with SRoll from both sets of TOIs. In the second case, the CMB anisotropies are added at the map level after the mapmaking. The difference between these two tests shows that we can avoid including the loop over many CMB cosmological signals at the TOI level.

Figure B.5 shows this difference at the power spectrum level. When the CMB is simulated at the TOI level, the calibration distortion is applied to the CMB and then solved by SRoll. All differences are much smaller than the signal, showing that the CMB can indeed be added to the residual map, i.e.,

$$[I, Q, U]_{\text{sim}} = [I, Q, U]_{\text{residual}} + [I, Q, U]_{\text{CMB}}.$$  (B.9)

The difference is typically less than one percent of the fiducial $EE$ spectrum for the CMB channels (it is higher at 353 GHz, but this channel is only used to remove the dust from CMB channels after multiplication by factors smaller than 10^{-2}).

The $TT$, $EE$, and $BB$ power spectra are then computed with Spice (Szapudi et al. 2001) from the output maps, using 50% of the sky if not otherwise specified. Then these power spectra are compared with the fiducial $TT$, $EE$, and $BB$ spectra.

This also demonstrates that SRoll does not significantly affect the CMB anisotropies in any way and that the systematic effects can be treated as additive. This is an important result, but not entirely surprising because the dominant polarized systematics are the residual dipole leakage from calibration mismatch and the residual foreground leakage from bandpass mismatch, both of which produce spurious polarization signals that add to the CMB anisotropies. The distortions of the CMB anisotropies themselves are much lower than the noise and therefore negligible.

---

#### Table B.1. Relative error on the gain given the number of iterations for different foreground levels.

<table>
<thead>
<tr>
<th>Iterations</th>
<th>No foreground</th>
<th>Low foreground</th>
<th>High foreground</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$\eta = 0$</td>
<td>$\eta = -0.08$</td>
<td>$\eta = -0.8$</td>
</tr>
<tr>
<td>1</td>
<td>$4.9 \times 10^{-29}$</td>
<td>$9.6 \times 10^{-4}$</td>
<td>$9.6 \times 10^{-3}$</td>
</tr>
<tr>
<td>2</td>
<td>$8.9 \times 10^{-6}$</td>
<td>$8.9 \times 10^{-4}$</td>
<td>$8.9 \times 10^{-4}$</td>
</tr>
<tr>
<td>3</td>
<td>$9.9 \times 10^{-8}$</td>
<td>$9.9 \times 10^{-5}$</td>
<td>$9.9 \times 10^{-5}$</td>
</tr>
<tr>
<td>4</td>
<td>$1.2 \times 10^{-9}$</td>
<td>$1.1 \times 10^{-9}$</td>
<td>$1.1 \times 10^{-9}$</td>
</tr>
</tbody>
</table>

---

#### Fig. B.4. Masks used during the mapmaking solution. The fraction of the sky used is $f_{\text{sky}} = 0.862$ at 100 GHz, $f_{\text{sky}} = 0.856$ at 143 GHz, $f_{\text{sky}} = 0.846$ at 217 GHz, and $f_{\text{sky}} = 0.862$ at 353 GHz.
B.3.2. Foregrounds

The foreground model used in the simulations is based on the Planck Sky Model v1.9 (Delabrouille et al. 2013), in which each foreground template is convolved with the ground-measured bandpass, leading to realistic bandpass leakage levels.

B.3.3. ADC non-linearity

We build a simple four-parameter model of the ADC non-linearity that remains after the correction at the TOI level using measurements performed during the warm phase of the mission. The most significant residual after this correction is the central discontinuity in the ADC. Our model of the residual non-linearity is constructed as a function of the ADU value. The central discontinuity is a step, but it is smeared out by the noise in the data, so we model it as the derivative of a Gaussian. The left column of Fig. B.6 shows the gain as a function of ADU value for four representative bolometers. The values determined by SRo11 from the data are shown as blue points. The red line shows the best-fit model for these gains, and the pink area surrounding it is the standard deviation of a four-parameter model of the residual ADC non-linearity fitted to these data. The right column shows gain as a function of pointing period, and shows that the model is able to reproduce the broad features of the remaining gain variation observed during the mission.

B.3.4. Low frequency transfer function

Low-frequency transfer functions are not simulated, but are nevertheless solved by SRo11. The fitted parameters are thus expected to be zero. The residual low-frequency transfer function patterns after SRo11 are then interpreted as degeneracies with other simulated systematic errors. The main aim of the resolution of this transfer function is to model the very long time constants (VLTCs) that were not characterized at the TOI level.

B.3.5. Noise

The noise is assumed to be Gaussian and stationary throughout the mission (see Sect. 2.3). The noise is simulated by drawing a realization for each pointing period from the measured noise power spectrum of each bolometer and its readout chain. Correlations between bolometers are not included in the model.

B.4. Validation and performance

B.4.1. Bandpasses

Figure B.7 shows the error on the reconstructed leakage coefficients, normalized to the average of all detectors in a frequency band, for the three main foregrounds in the HFI channels (dust, CO, and free-free). Although the dispersion is in some cases larger than the statistical noise, the accuracy is better than one percent, and small enough to induce negligible effects on the gain determination and the sky maps produced by SRo11. The excess variance of the bandpass leakage distribution at 100 and 353 GHz is probably due to the degeneracy between the main leakage sources (CO and dust). This is further confirmed by the extreme stability of the inter-calibration of the 100, 143, and 217 GHz detectors (see Fig. 13), which have rms dispersions in the range $0.5 - 2 \times 10^{-3}$. 

Fig. B.5. Power spectra of the differences between maps made from TOI including the CMB, and maps made from TOI including only noise and systematics with the same CMB added to the map. In this simulation run, the CMB power spectra are set to $F_{-EE}$.

Fig. B.6. Evolution of the gain solved by SRo11 for four representative bolometers. The left column shows gain as a function of signal level in ADU, with values determined from the data in blue. The red line is the best fit, and the pink area surrounding it is the standard deviation of a four-parameter model of the residual ADC non-linearity fitted to these data. The right column shows gain as a function of pointing period, and shows that the model is able to reproduce the broad features of the remaining gain variation observed during the mission.
Fig. B.7. Error on the recovered leakage coefficients solved by SRoll, normalized to the average of all detectors in a frequency band, on a representative set of detectors. The error bars (in red) are the statistical distribution from 20 realizations of the simulations.

Fig. B.8. Residual auto-power spectra of the CO bandpass leakage residuals.

Fig. B.9. Residual auto-power spectra of the dust bandpass leakage residuals.

Fig. B.10. Residual auto-power spectra of the free-free bandpass leakage residuals.

B.4.2. ADC non-linearities

Synchrotron emission is weak in the HFI channels (see Sect. 5.2), and so the synchrotron leakage will be even weaker. Estimates using bandpasses from ground measurements show that it is negligible.

Using the reconstructed leakage coefficients, the corresponding templates, and the pointing, we build maps of the residual bandpass leakage. Figures B.8–B.10 show the power spectra of those maps for CO, dust, and free-free foregrounds, respectively. These are negligible with respect to the fiducial EE spectrum at 100, 143, and 217 GHz. The 353 GHz channel is used only to clean the dust emission from the CMB channels, so the additional leakage induced in these channels will be scaled down by the coefficients used to do the cleaning (factors of $3.5 \times 10^{-5}$, $1.7 \times 10^{-3}$, and $1.6 \times 10^{-2}$ at 100, 143, and 217 GHz, respectively).

The full ADC non-linearity induces distortions in the signal at low multipoles (as shown in Sect. 2.5), which are mostly corrected at the TOI level. We investigate here the residuals after the TOI-level correction, as well as the secondary correction applied to them in the mapmaking, using the model described in Sect. B.3.3. Figure B.11 shows the results of ADC non-linearity simulations for four representative bolometers. We simulate the non-linearity using these simulations. The gains reconstructed by SRoll from 20 realizations are shown with a red line (mean) and pink band (standard deviation). These can be compared to the blue line, which shows the gain variation computed directly from the input ADC model. The difference between the blue and red lines averaged over the mission gives the average bias on the gain (shown in each panel as “AVG BIAS”) from 1 to $5 \times 10^{-5}$ in the CMB channels, and $4 \times 10^{-4}$ at 353 GHz.
Fig. B.11. Gain variations solved by SRoll (red line; the light red band shows the variance of 20 noise simulation realizations) compared to the gain variation computed directly from the input ADC model (blue).

Fig. B.12. Residual auto-power spectrum of the ADC non-linearity corrected by the gain variation model.

The results of the simulations are the residual power spectra of the ADC non-linearity corrected for the gain variation model, shown in Fig. B.12. The residuals in EE for 100 and 143 GHz are low for $\ell > 30$, but close to the level of the fiducial EE spectrum for the reionization peak at $\ell = 2–3$. At these frequencies, the apparent gain correction and inter-frequency calibration from SRoll have been shown to be very accurate (see Fig. B.11 and Table B.2).

Figure B.13 shows the residual polarization maps averaged from six simulations of the 100 GHz channel without noise. The left column shows the residuals obtained when the data are simulated using a linear model with a gain that is constant for each ring, but that varies over the mission. This is the model that SRoll fits to the data. It is able to recover the gains almost exactly, so the residuals are at a very low level. The right column shows a simulation including the complete effect of the residual ADC non-linearity. The additional residuals seen in this case are produced by the distortion of the dipole signal that SRoll does not correct. The associated power spectra explain the low-$\ell$ power spectrum residuals in Fig. B.12, as is demonstrated below for one specific detector.

Figure B.14 shows maps from the same simulations of the ADC non-linearity (left column) compared to the data (right column) for the 100 GHz channel. The first row shows the maps made before correcting the ADC non-linearity with the SRoll variable gain model, which demonstrates that the simulations can effectively reproduce the effect seen in the data. The second row shows maps made after correction with the SRoll variable gain model. The large-scale patterns seen in the first row are mostly removed by this correction. The dipole distortion shown in Fig. B.13 is still present, but is partly hidden by the noise. The third row shows the map of the simulation when the ADC non-linearity is not introduced, and contains only noise. The dipole distortion is not present in this map. This is a clear indication that the only residual remaining after the SRoll mapmaking is small and comparable to the noise at $\ell > 10$, and exceeds those only at $\ell = 2–3$.

We have shown that maps made by SRoll contain a residual ADC non-linearity effect from the distortion of the dipole, which cannot be corrected by the variable gain model. The distortion of the dipole can nevertheless be predicted using the gain-variation-based model of the non-linearity shown in Fig. B.6 and described in Sect. B.3.3.

B.4.3. Residual complex transfer function

The correction applied to the VLTC only accounts for the shifts in the dipole that it produces, which had previously allowed us to use the orbital dipole for calibration. It is clear that there must be some time constants with low amplitudes affecting the data at low multipoles beside the dipole, which lead to additional small in-scan shifts. The FSLs lead to a cross-scan shift which is cancelled to first order in the sum of odd- and even-survey data, but which leaves an amplitude effect in the cross-scan signal. Finally, the so-called baffle components of the FSLs is not
correctly described by the first-order GRASP model used to remove them. This produces an extra in-scan shift and change in the amplitude. We therefore fit for empirical transfer functions to account for these small residuals. These transfer functions are fitted for four ranges of harmonics of the spin frequency (1, 2–3, 4–7, and 8–15). The accuracy of the reconstruction of the corresponding amplitudes is estimated by using the simulations. Figure B.15 shows the mean and standard deviation of the reconstructed amplitudes from 20 realizations of a simulation where no extra transfer functions were included, so the true value is zero in all cases. The results are consistent with zero within the statistical uncertainties. Therefore we conclude that the degeneracies with the other systematic effects are small and that this correction for the residual transfer function will be accurate at the level of the noise.

Figure B.16 shows that the residual transfer functions in the maps lead to a negligible residual in the power spectrum for the CMB channels. The 353 GHz channel shows an effect close to the level of the fiducial signal, but this channel is used only to clean the CMB channels, so the residuals added to those channels by this process are scaled down by the corresponding cleaning coefficients (as discussed before for other simulations).

**B.4.4. Noise**

Figure B.17 shows power spectra of null tests on detector sets and half missions. The blue lines show the data, and the red lines and error bars show the mean and standard deviation of simulations containing noise alone. There is no evidence for unseen systematics in these null tests.

**B.4.5. Calibration mismatch**

The difference between the mean of the input variable gain and the mean of the variable gain solved for by SRoll gives an estimate of the calibration mismatch in the final maps. Table B.2 shows the minimum, maximum, and rms of the detector calibration in each frequency band. The very low values of the rms of
channels, and at the level of the fiducial signal at 217 GHz. At 353 GHz, the ADC-induced apparent gain variations are only a factor of a few below the noise at very low multipoles. The bandpass leakage is only a small factor lower. The noise itself is low compared to the dust signal at high latitude (more than two orders of magnitude). It is therefore far below the fiducial signal when scaled with the appropriate coefficients to clean the 100 and 143 GHz maps. In the CMB channels, the dipole distortion (not removed from the data) is significant and particularly strong at very low multipoles. At 353 GHz, the systematic effects are negligible if this channel is only used to clean dust emission from the channels used for measuring $\tau$.

Appendix C: LFI low-$\ell$ polarization characterization

Here we provide a summary of the Low Frequency Instrument (LFI) systematic effects that are most relevant for the polarization analysis at low multipoles. A detailed discussion of all systematic effects for the LFI 2015 release is given in Planck Collaboration III (2016).

We have developed time-dependent models for the known systematic effects in LFI. For each effect, we generate a timeline and project it into the map domain using the same pipeline used for the data, including the Planck scanning strategy and LFI mapmaking process. We call the resulting maps “systematics templates” and quantify the impact of these systematic effects by comparing their power spectra to the FFP8 simulations (which reproduce the measured LFI noise spectra, Planck Collaboration XII 2016), and to the recovered sky signal.

Figure 23 summarizes the results of our analysis for $\ell < 45$ (resolution approximately 4'). For EE polarization, the most relevant effects come from uncertainties in the radiometer gains. ADC non-linearity and sidelobe residuals (at 30 GHz) contribute at a lower level. We discuss each of these three sources of systematic effects in turn.

C.1. Gain reconstruction

The gain of a balanced differential coherent receiver may vary at the 1% level on a variety of timescales, depending primarily on changes in the thermal environment or the bias. For each LFI radiometer, we recover the gain changes as a function of time using the solar dipole (Planck Collaboration V 2016). Imperfect recovery of the true radiometer gain variation produces a systematic effect. The gain solutions are least accurate when the dipole signal is near its minimum, typically a period of several days, which produces effects at large angular scales. At multipoles $\ell < 30$ for Stokes $Q$ and $U$, the rms effect is 0.4 $\mu$K at 30 GHz, 0.3 $\mu$K at 44 GHz, and 0.15 $\mu$K at 70 GHz. These are the dominant systematic errors in the present analysis.

C.2. ADC correction

Deviations from linearity in the ADC response impact the LFI differently than the HFI. Linearity in the ADC requires that the voltage step size between successive binary outputs is constant over the entire signal dynamic range. Deviations from this ideal behaviour affect the calibration solution. Because the effect induces a variation of the detector white noise that is not matched by a corresponding variation in the absolute voltage level (which would be expected from LFI radiometers), the anomaly can be measured and corrected. We evaluate the residual error through simulations. Since the radiometer gain varies coherently over
periods of days to weeks, the average output of the radiometer (and therefore the part of the ADC range being used) also varies on this timescale. Imperfect removal of ADC effects thus produces residuals at low multipoles. Additionally since the effect is independent for each ADC channel, it is not mitigated by differencing orthogonally polarized radiometers. As a consequence, the amplitudes of the residuals are comparable for temperature and polarization, implying of course a larger scientific impact on polarization. For the $Q$ and $U$ components at large scales, the rms residual effect is $<0.1 \mu K$ at 30 and 44 GHz, and approximately $0.15 \mu K$ at 70 GHz.

### C.3. Impact of sidelobes

Telescope sidelobe response can be relevant at low multipoles, both directly and through the calibration process; this is particularly the case at 30 GHz. To deal with this, we remove a model of the sidelobe signatures (“stray light”) in the LFI timelines by combining the GRASP models of the beams with the measured sky maps at each frequency (Planck Collaboration IV 2016). To test the impact of imperfectly modelled sidelobes on the calibration, we ran our calibration simulation pipeline in a mode where we typically use a single QML cross-spectrum. The $\hat{C}_{\ell}^{\text{EE}}$ estimator (pseudo-) cross-power spectra are then constructed from a pair of maps. The $\hat{C}_{\ell}^{\text{EE}}$ estimator can be built from HFPS1 (or HFPS2) for the central part of the fit; the HFPS3 simulations. The two distributions (blue and green curves). Despite the limited number of simulations available, the impact is negligible primordial tensors. The degeneracy between these two parameters can then be broken by an accurate measurement of the $E\ell=\ell\tau$ polarization feature since this depends roughly on $A_{\ell}e^{-2\ell\tau}$, which is linearly independent of the high-$\ell$ constraint. We thus develop a “simulation-based likelihood” code, named SimBal, which is focused on $\tau$ estimation, and based on $EE$ (pseudo-) cross-power spectra $\hat{C}_{\ell}$, using either PCL or QML estimators.

Given our current understanding of systematic errors, in SimBal we typically use a single QML cross-spectrum $\hat{C}_{\ell}$ constructed from a pair of maps. The Planck maps, at 100 and 143 GHz, are each ILC-cleaned using 30 and 353 GHz maps as foreground tracers, as described in Sect. 5.2. The low dimensionality of the problem renders the likelihood analysis amenable to a scheme based on computing $P(\tau | \hat{C}_{\ell}^{\text{data}}, \Omega)$, where $\Omega$ stands for the other cosmological and non-cosmological parameters. We formally have some freedom in the choice of $\Omega$, but typically use best-fit values from the Planck cosmological parameter analysis (Planck Collaboration XIII 2016). More explicitly, we follow these steps.

1. Compute the power spectra of simulations $\hat{C}_{\ell}^{\text{sim}}$ for various $\tau$ values, including noise and systematic effects.

![Fig. D.1. Distribution of the SimBal $\hat{t}$ estimator from signal-free HFPS1 and HFPS1+HFPS3 simulations. The two distributions (blue and green dashed lines) are consistent with a Gaussian width $\sigma = 0.015$ for the relevant numbers of simulations. The $\hat{t}$ value from the data (in red) is incompatible with these simulations at the 3.5$\sigma$ level.](image)

2. Compute $P(\hat{C}_{\ell}^{\text{sim}} | \ell, \tau, \Omega)$, fitting $\ell$-by-$\ell$ a model to the simulated power spectra. This model is needed in order to reduce noise and to extrapolate beyond the measured range, given by the simulations (see Sect. D.4 for more details). The SimBal model uses:
   
   $$ \ln \left( \frac{P(\hat{C}_{\ell}^{\text{sim}} | \ell, \tau, \Omega)}{P(\hat{C}_{\ell}^{\text{data}} | \ell, \tau, \Omega)} \right) = A(\ell), $$
   
   where $A$ is a 3rd-order polynomial, for the central part of the fit; and
   
   $$ \ln \left( \frac{P(\hat{C}_{\ell}^{\text{sim}} | \ell, \tau, \Omega)}{P(\hat{C}_{\ell}^{\text{data}} | \ell, \tau, \Omega)} \right) = B(\ell), $$
   
   where $B$ is a 1st-order polynomial, for both tails of the fit.

3. Compute the $\hat{t}$ estimator, which is closely related to $\tau$, but easy to compute on pseudo-$C_{\ell}$ spectra:

   $$ \hat{t} = \arg \max_{\tau} \sum_{\ell=\ell_{\text{min}}}^{\ell_{\text{max}}} \ln \left( P(\hat{C}_{\ell}^{\text{data}} | \ell, \tau, \Omega) \right). $$

(D.1)

4. Use simulations to determine $P(\hat{t} | \tau, \Omega)$.

5. Finally deduce $P(\tau | \hat{t}, \Omega)$ from $P(\hat{t} | \tau, \Omega)$.

The simulation set $\hat{C}_{\ell}^{\text{sim}}$ is built from HFPS1 (or HFPS2) for the noise and systematic effects, to which we add 100 CMB realizations. We then use the simulations described above to construct the sampling distributions $P(\hat{C}_{\ell}^{\text{sim}} | \ell, \tau, \Omega)$, for a grid of $\tau$ values from 0.010 to 0.180, in steps of 0.001. The relatively low number of noise simulations leads to some apparent features in the distributions, particularly at low $\tau$ where the CMB contribution is smaller; however, for a given number of simulations, this would affect the result only of the lowest $\tau$ values. Considering the number of simulations we have, this does not affect our results for the range of $\tau$ values considered in Sect. 6.

Figure D.1 shows the $\hat{t}$ found with the data (red vertical line) compared to the $\hat{t}$ distribution computed on simulations with noise and systematic effects, but without signal (green and blue curves). Despite the limited number of simulations available, the...
Fig. D.2. Distribution of the $\tau$ probability density as a function of the $\hat{\tau}$ estimator (defined in the text) derived from the $100 \times 143$ cross-spectra. The top panel uses simulations containing only white noise, while the bottom panel uses simulations with the systematic effects residuals added. As an example of a cut through this two-dimensional plot, in the top panel an observed value of $\hat{\tau} = 0.057$ (horizontal black line) gives a probability distribution (red curve) that peaks at $\tau = 0.060$. In the bottom panel, the same peak value of the probability distribution is obtained with an observed $\hat{\tau} = 0.065$.

Fig. D.3. Pixel-pixel matrix $\chi^2$ values of the first 400 of the 143 GHz FFP8 simulations, evaluated against 18-arbitrary-eigenmode fits to either the first 50, 83, or 200 simulations. The $\chi^2$ of the simulation data set used to compute the pixel-pixel covariance matrix has been normalized here. Due to the limited number of simulations, the real variance, estimated from the simulations that were not used to compute the pixel-pixel matrix, is significantly higher (i.e., the red line jumps at about 50, the green line at about 83, and the blue line at about 200).

D.2. Illustration of the method

Figure D.2 shows an illustration of the method for the $100 \times 143$ cross-spectra. The top panel shows, for white noise only, the joint probability distribution in the $(\hat{\tau}, \tau)$ plane, assuming a uniform prior on $\tau$. For a given value of $\hat{\tau}$, the red curve shows the probability distribution of $\tau$, which peaks at a value close to the value of $\hat{\tau}$ by construction of the definition of $\hat{\tau}$. The bottom panel is built using the HFPS1 simulations (with systematic effects) and 100 CMB simulations. In this case, for low values of $\tau$, the maximum of the probability distribution shifts slightly from the diagonal because of the inclusion of the systematic effects. In the top panel the value $\hat{\tau} = 0.057$ gives a probability distribution that peaks at $\tau = 0.06$. When using the simulations that include systematic effects (bottom panel), the value $\hat{\tau} = 0.065$ gives a peak value of $\tau = 0.06$. When a data power spectrum gives this value of $\hat{\tau} = 0.065$, we determine with simulations that not including the systematic effects would produce a positive bias of about 0.008 in $\tau$. When we include the systematic effects in the simulations, we show our method is able to recover unbiased estimates of $\tau$ with an uncertainty small compared to the noise.

D.3. Noise variance

Figure D.3 shows the $\chi^2$ values of low resolution maps from FFP8 noise simulations (see Planck Collaboration XII 2016) evaluated with covariance matrices built with an increasing fraction of the simulations. This illustrates the difficulty introduced by having only a limited number of simulations with which to estimate a low-resolution noise covariance matrix and then to evaluate properties of statistical distributions involving this covariance matrix. Each covariance matrix is computed from a subset of the available simulations, rescaling a fiducial covariance matrix and then adding extra modes to capture the additional systematic effects. It can be seen that the simulations that are not used to build the covariance matrix have a higher $\chi^2$ than those used to build the matrix. Hence using the same simulations twice gives a misleadingly low indication of the scatter (note that increasing the number of simulations used to fit the noise matrix decreases the $\chi^2$ discrepancy, as one would expect). Thus, to take into account this feature in the likelihood, SimBaL uses two
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Fig. D.4. Probability slice at $\ell = 4$ for two different $\tau$ values, $\tau = 0.025$ (top panels) and $\tau = 0.06$ (bottom panels). The left panels show the signal-only distribution, while the right ones show the signal plus noise and systematic effects. For small $\tau$ values, the distribution is dominated by noise and systematic effects and is fitted poorly by the Hamimeche-Lewis-type model (red line), but is well-captured by the SimBaL polynomial approximation (blue curve).

D.4. Dependence on the model

SimBaL uses simulations of noise and systematic effects, to which are added 100 CMB realizations, in order to model the statistical distribution of $\ln\left(P(\hat{C}_\ell|\ell, \tau, \Omega)\right)$ for each $C_\ell$. We fit this distribution for each multipole using an asymmetrical polynomial function detailed in Sect. D.1. Figure D.4 shows how the SimBaL polynomial approximation is efficient in capturing the shape of the probability distribution for low $\tau$ values when systematic noise effects dominate, while a SimBaL_HL approximation (based on a Hamimeche & Lewis model, Hamimeche & Lewis 2008) is a poor fit to the probability distribution tails for low values of $\tau$. Figure D.5 shows the effect of these two models on the $\tau$ posterior computation. SimBaL_HL modelling overestimates the probability of small $\tau$ values, where the distribution is dominated by noise and systematic effects.

D.5. Dependence on masks

Figure D.6 shows four sky masks with $f_{\text{sky}}$ ranging from 0.30 to 0.60, built by thresholding the intensity of the Galactic polarized emission. Figure D.7 shows the effects of sky masking on PCL $\tau$ posteriors for the data. This shows that the effect of varying the retained sky fraction is small. In the main likelihood analysis, the mask used is the one with $f_{\text{sky}} = 0.50$, which is in fact the sky fraction that yields the best accuracy (smaller posterior width). Even for the more extreme sky fraction used there is a small bias (of around $0.4\sigma$) towards lower peak values for the $\tau$ probability distribution. The generally very good consistency between these curves around the used $f_{\text{sky}} = 0.50$ shows that the component-separation process is not a limitation in the determination of $\tau$ in this paper.

D.6. Dependence on multipole range

Figure D.8 shows the effect of changing the range of multipoles used in the $100 \times 143$ PCL cross-power spectrum. As expected, using a minimum $\ell$ of 5 or 6 starts to bias the result because of the low level of the reionization feature above these multipoles. Although we know that the effects of ADC non-linearity on the

Fig. D.5. Posterior distributions of $\tau$ from SimBaL (blue curve) and SimBaL_HL (red curve), showing how they differ at low $\tau$. The red line is an attempt to mimic in SimBaL the modified “HL” approach, and demonstrates that the divergence is due to residual non-Gaussian behaviour of the statistics at low multipoles (see text).

Fig. D.6. Masks for different values of $f_{\text{sky}}$. The mask shown in the bottom-left panel (50% sky fraction) is the one used in the Lollipop and the SimBaL analyses. The other three were used to evaluate the dependence of the results on changing sky fractions from 30 to 60%.

Fig. D.7. Effects of sky masking on PCL $\tau$ posteriors for the data. This shows that the effect of varying the retained sky fraction is small. In the main likelihood analysis, the mask used is the one with $f_{\text{sky}} = 0.50$, which is in fact the sky fraction that yields the best accuracy (smaller posterior width). Even for the more extreme sky fraction used there is a small bias (of around $0.4\sigma$) towards lower peak values for the $\tau$ probability distribution. The generally very good consistency between these curves around the used $f_{\text{sky}} = 0.50$ shows that the component-separation process is not a limitation in the determination of $\tau$ in this paper.
dipole are concentrated at $\ell = 2$ and 3 before removal, including these multipoles does not affect the result substantially. This is an important result as it confirms that this systematic effect residuals in the cross power spectra are small as discussed in Sect. 5.3.1 and accurately simulated in the HFPS, and accounted for when used in the SimBaL likelihood.

Figure D.9 shows the effect of removing one multipole at a time from the QML results. Except for the case of removing $\ell = 5$, which is the multipole where the EE cross-power spectrum is maximum and the probability to exceed near 2 $\sigma$ (see Fig. 33), we obtain very stable results. Figure D.10 shows how removing one multipole from the $\tau$ posterior computation where the power spectrum is maximum does bias the result low as expected; however, the $\tau$ value obtained when removing $\ell = 5$ is statistically consistent with what is expected from simulations.

As a consequence of this discussion, the likelihood analysis in this work uses the multipole range 2–20.

D.7. SimLow: a low-$\ell$ likelihood based on SimBaL
SimBaL provides a $\tau$ posterior using the other parameters based on the best cosmology from the $TT$, $TE$, and $EE$ power spectra at higher multipoles. Thus, SimBaL is not usable as a low-$\ell$ likelihood for cosmological parameters that are not the ones used...
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Fig. D.11. $P(C^\text{fid}_\ell \mid C^\text{data}_\ell)$ computed for the data using SimLow. Power spectrum values computed for different $\tau$ are shown in blue. For $\ell = 3$ and $\ell = 5$ we can see that very small values of $\tau$ are excluded, while for $\ell = 4$ large values of $\tau$ have a low probability.

In order to measure $P(C^\text{sim}_\ell \mid C^\text{fid}_\ell)$ for the $100 \times 143$ power spectrum, we compute 100 realizations of each $C^\text{fid}_\ell$, with 3000 steps of $10^{-4}$ $\mu$K$^2$ added to the HFPS1 and HFPS3 simulations using the QML2 estimator for the power spectra. Figure D.11 shows the results of running SimLow for the first few multipoles of the data.

SimLow uses posteriors for multipoles in the range $\ell = 2$–20. Using SimLow to compute the $\tau$ posterior with the same cosmological parameters as SimBaL (Fig. D.12) gives $\tau = 0.055 \pm 0.009$, which is fully consistent with the value from SimBaL and referred to as lowEH.

Appendix E: Glossary

This Appendix gathers definitions of acronyms and other terms widely used in this paper, in addition to those more general terms listed in the glossary and acronym list of Planck Collaboration (2015).

ADC non-linearity: analogue-to-digital converter non-linearities. The HFI bolometer readout electronics includes a 16-bit ADC that has a very loose tolerance on the differential non-linearity (the maximum deviation from one least significant bit, LSB, between two consecutive levels, over the whole range), specified to be not worse than one LSB. The implications of this feature for HFI performance proved to be a major systematic effect on the flight data. A wide dynamic range at the ADC input was needed to both measure the CMB sky and foregrounds, and properly characterize and remove the tails of glitches from cosmic rays. Operating HFI electronics with the necessary low gains increased the effects of the ADC scale errors on the CMB data (see Sect. 2.1 of Planck Collaboration VIII 2016, for further details).

ADU: analogue-to-digital unit.

Complex transfer function: an empirical function that captures residuals of the bolometer/electronics time response deconvolution (including VLTC) as well as residuals from far sidelobe effects.

Detset or ds: “detector set”, i.e., a combination of sets of polarization-sensitive bolometer pairs with both orientations. Specifically, 100 GHz ds1 combines 100-1a/b and 100-4a/b, 100 GHz ds2 combines 100-2a/b and 100-3a/b, 143 GHz ds1 combines 143-1a/b and 143-3a/b, and 143 GHz ds2 combines 143-2a/b and 143-4a/b.

Distorted dipole: the difference between the actual dipole signal (which is affected by the ADC non-linearity, like all signals) and the sine wave that would have been measured without the non-linearity.

F-TT, F-EE, and F-BB models: CMB fiducial power spectra, based on best-fit Planck cosmological parameters (Planck Collaboration XIII 2016), with $\tau = 0.066$ and $r = 0.11$. 

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FSL: far sidelobe, i.e., the pickup of the sky signal, dominated by the spillover of radiation around the edges of the secondary and the primary telescope mirrors after being reflected by the secondary mirrors and main baffle (with the usual convention following the light from the detectors outwards).

HFPS: HFI focal plane simulations, built with the pre-2016 E2E software pipeline. They contain realizations of the noise described in Sect. B.3.5, with the systematics dominated by the additional ADC non-linearity model described in Sect. B.4.2. HFPS1 contains 83 realizations, while HFPS2 and HFPS3 each contain 100 realizations.

HPR: HEALPix ring, i.e., a partial map produced from projection onto a HEALPix-pixelized sky data from a single pointing period.

PCL: Pseudo-$C_\ell$ estimator, a specific method for deriving a cross-spectrum.

Pre-2016 E2E: end-to-end simulation pipeline, based on the 2015 E2E simulation pipeline, where the ADC non-linearity correction in the mapmaking process has been added to the TOI. The 4-K line and convolution effects are not simulated because that could affect the higher multipoles.

QML: quadratic maximum likelihood estimator method, a specific method used to derive a cross-spectra. The pixel-pixel covariance matrices (QML1 and QML2) are built using three different QML estimators. For QML1 (or QML2), the pixel-pixel matrix has been computed directly with the HFPS1 (or HFPS2) data set. For QML3, in order to minimize the effect of overfitting, the off-diagonal terms are reduced to the first four eigenmodes of a principal component analysis from HFPS1.

SimBaL1,2,3: three posterior distributions for $\tau$. They differ in the choice of the power spectrum estimator and the data set simulation used. SimBaL1 (or SimBaL2) uses QML1 (or QML2) as power spectrum estimator and HFPS2 (or QML1) as the simulation data set. SimBaL3 uses QML3 as power spectrum estimator and the full set of simulations (HFPS1+HFPS2+HFPS3) as the simulation data set.

SRoll: a new polarized destriping algorithm, which removes residuals via template fitting, using HPR to compress the time-ordered information.

VLTC: very long time constant, i.e., bolometer time response longer than 1 s, which even at low amplitude may bias the calibration by distorting the dipole signal and causing leakage of the solar dipole into the orbital dipole.